



Working With Waveforms

In this talk we illustrate tools for digital signal processing through application in several recent publications



Sebastian White LIP-IDTM Sept. 13, 2023



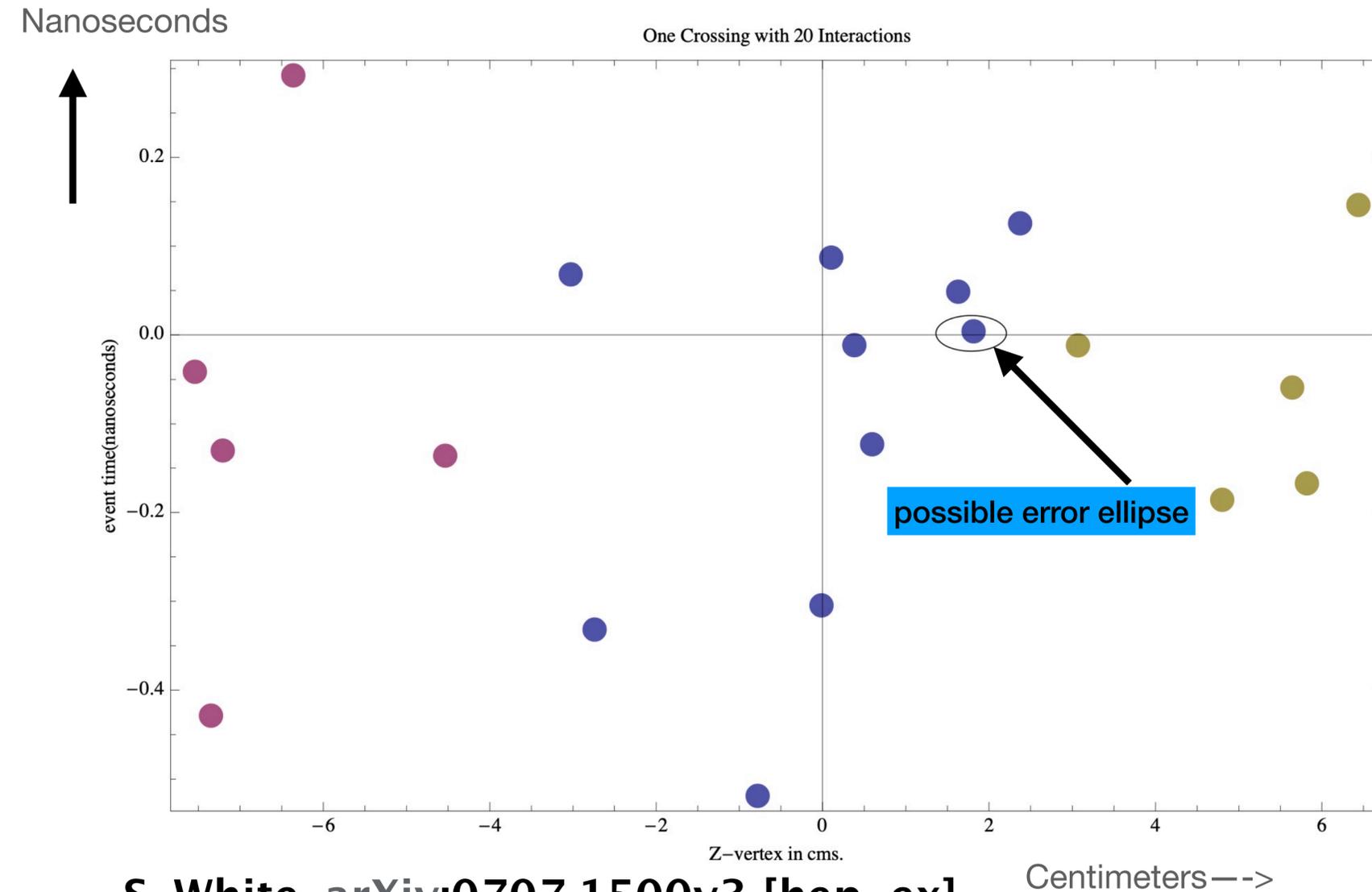
Bibliography/ Topics

- High Gain (aka Deep Diffused) Avalanche Diodes
 - “Deep diffused APDs for charged particle timing applications.....”, Vignali et al, NIM v 949, 162930 (Jan 2020)
- “PICOSEC” ~20 picosecond MPGD based MIP timing
 - See Florian Brunbauer, these proceedings (and NIM articles referenced therein).
- Single Delay Line Shaping applied to SiPMs w 10’s of GHz Dark Count Rate
 - S. White and A. Heering, “*Digitized waveform signal processing for fast timing: an application to SiPM timing in the presence of dark count noise*”, [2020 JINST 15 C04036](#)
- Use of CADENCE based Xfer Func’s to mock up ASIC performance with beam data
 - S. White, “**Virtual ASICs with Real Data**”, CPAD 2021, <https://arxiv.org/pdf/1712.05256.pdf>
- A new tool to mitigate time jitter from Dark Count noise
 - “Signal processing to reduce dark noise impact in precision timing”, S. White: [2023 JINST 18 P07051](#)
- Relating TOFHIR2C noise to effectiveness of above tool
 - Work in progress...

In this talk we discuss all but 1st 2 topics

necessity= mother of invention....

- In 2011 I moved to CERN==> Crispin Williams' Lab
- Had written paper in 2007 advocating 4D vertexing for pileup mitigation
- => R&D on fast timing sensors



S. White, arXiv:0707.1500v3 [hep-ex]

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Projects
High Gain AD w. M.Moll, Princeton, Penn,RMD, LIP

PICOSEC MPGD from 2015 w. Saclay, GDD +++

Resources
FEE: help from P. Farthuat, E. Griesmayer, Mitch Newcomer

DAQ: Lecroy very generous

+ prior work w. Wolfram-> "Mathematica for data"



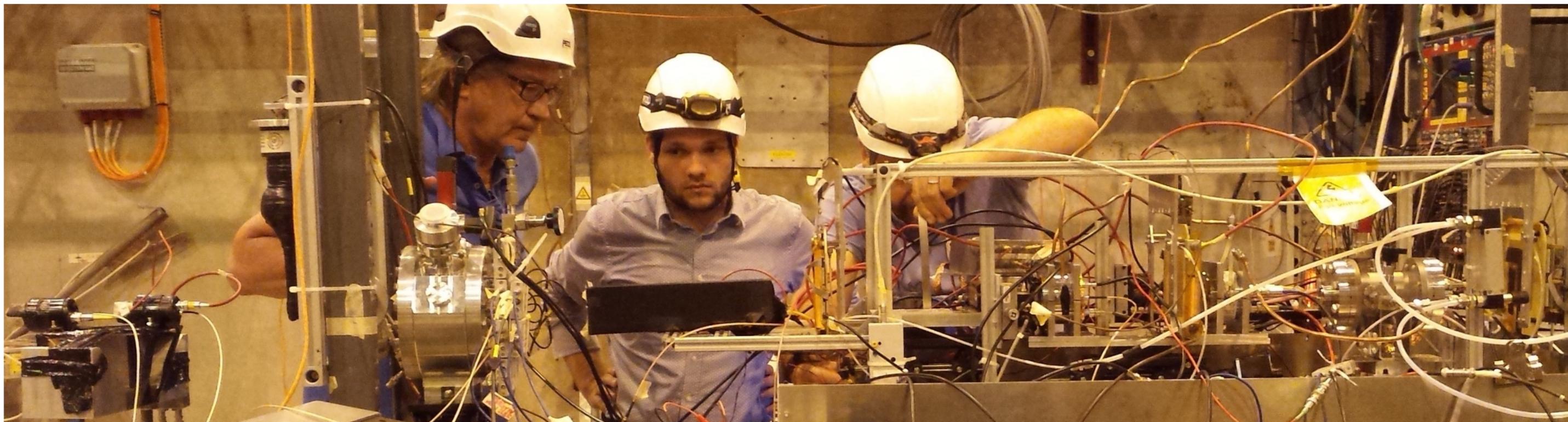
Erich G. working on input protection

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Lecroy down the road in Meyrin and very generous. Former collaborator Al. Rothenberg wrote their software

High Gain AD and PICOSEC shared resources: tracking, MCP-PMTs, and scopes



Typically all timing analysis from 1 to 2.5 GHz BW, 20 GSa/s or greater scopes.

Recently working w Eric Delagnes & Dominique Breton for PICOSEC.

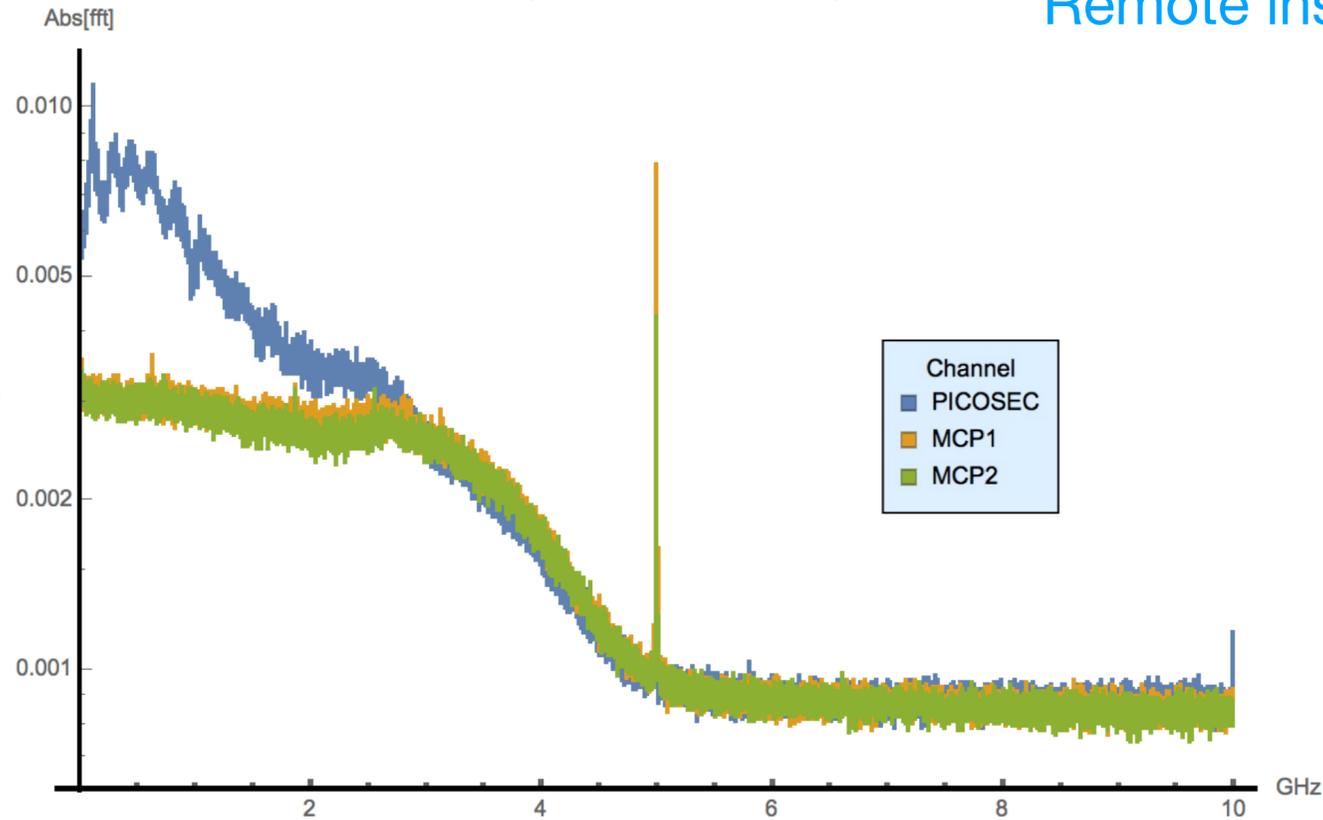
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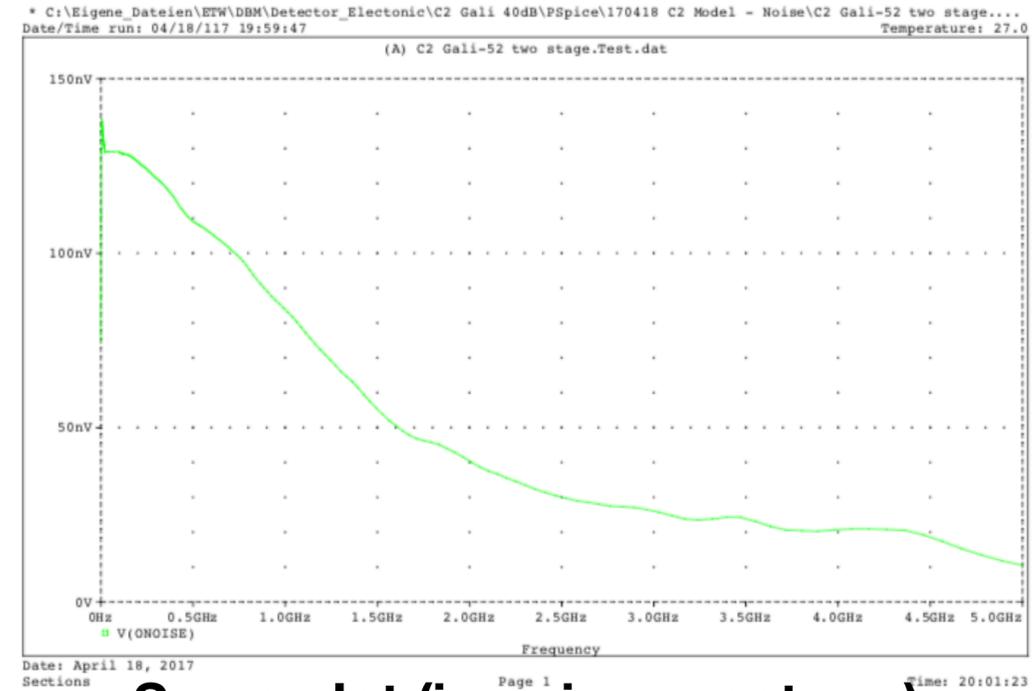
A Few applications: Discrete Fourier Transform-

Run284 Noise Spctrum, LRS 2.5GHz Scope, 20 GSa/s

Remote inspection of Noise Characteristics (CERN<-> CIVIDEC)



our test beam noise spectrum

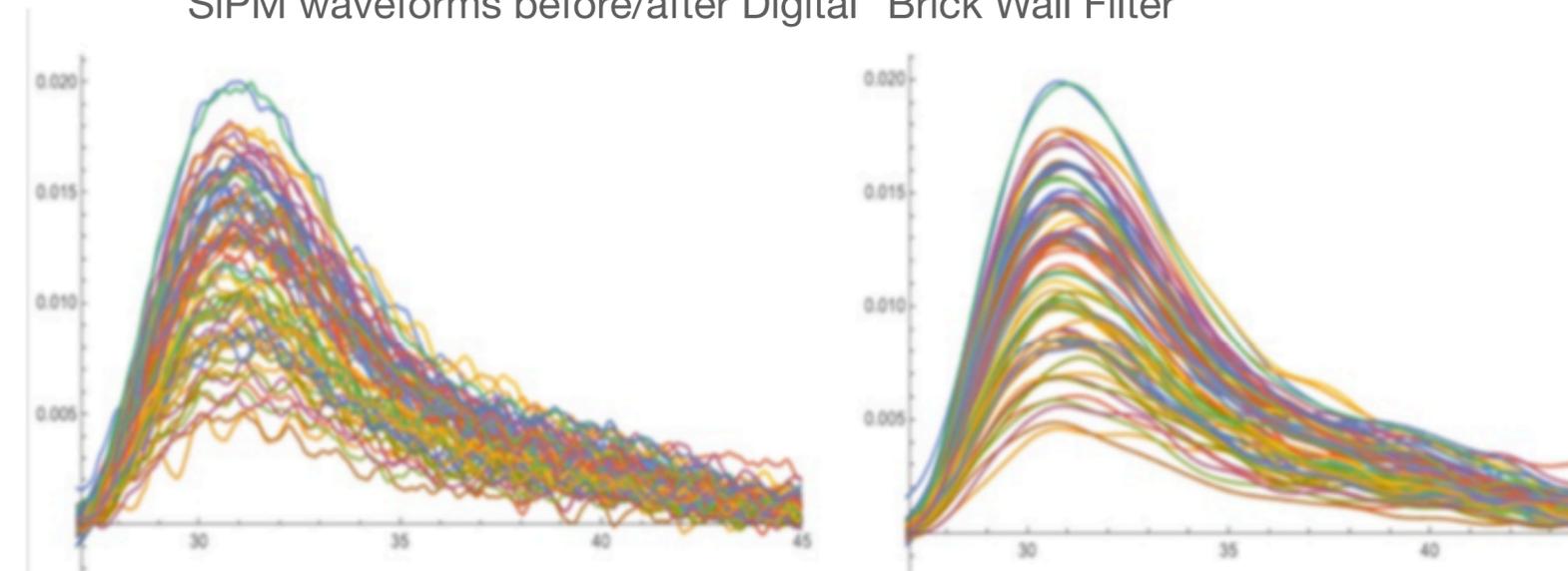


Same plot (ie noise spectrum) verified by E. Griesmayer(Cividec)- SPICE

After the fact removal of pickup noise from rf environment @ C. Joram lab at CERN "brick wall filter"

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SiPM waveforms before/after Digital "Brick Wall Filter"



Signal Processing to deal w Pileup and Dark Count Noise

Lab Measurements of SiPM Time Resolution vs. Irradiation

Sebastian White^a, Arjan Heering^b

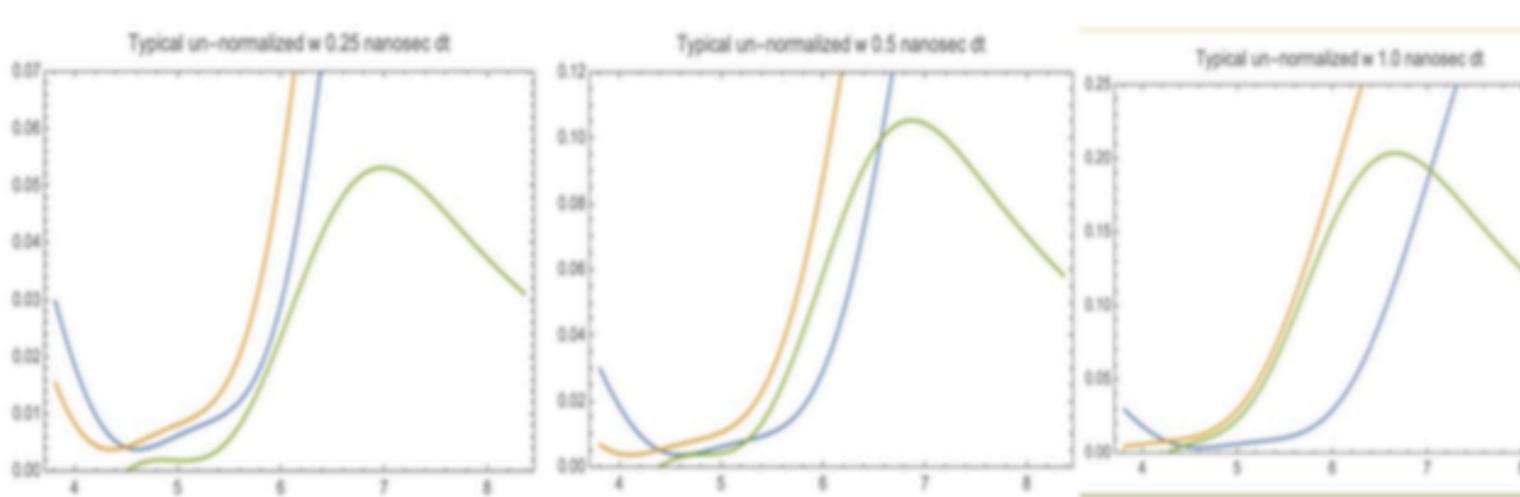
^aCERN/University of Virginia

^bNotre Dame

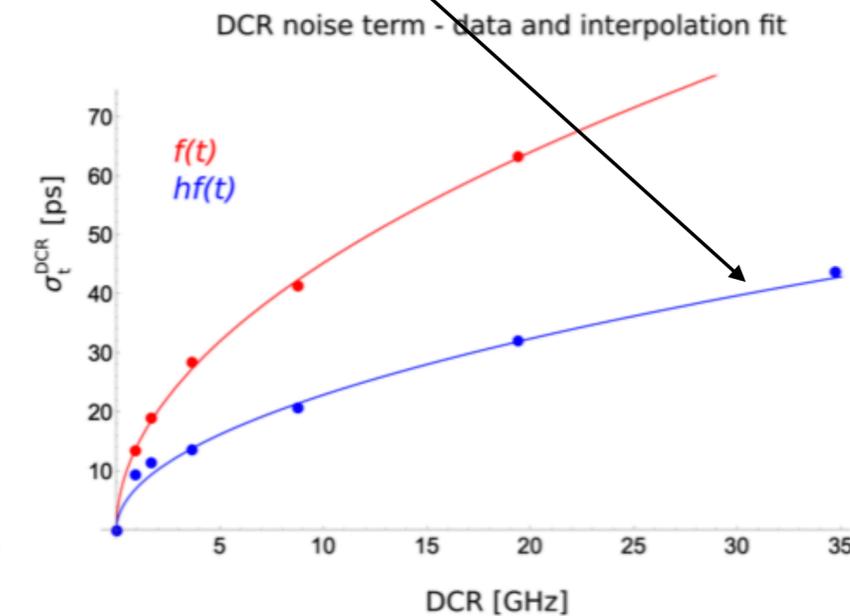
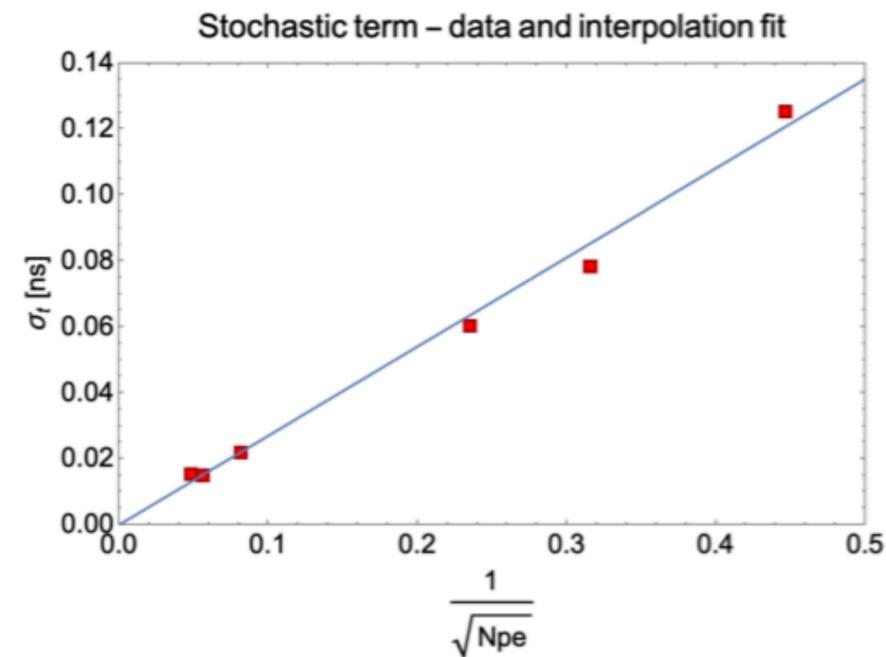
baseline restoration.
Signal processing algorithm, ie:

$$hf(t) = f(t) - f(t + dt)$$

mitigates timing degradation
due to dark count noise



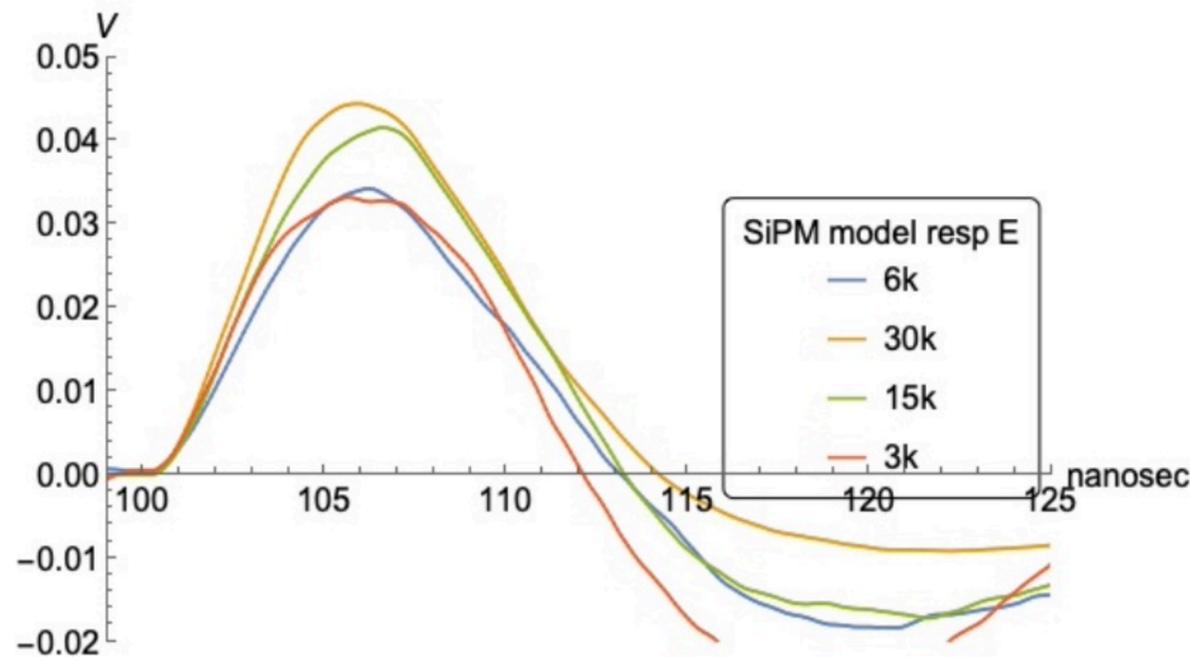
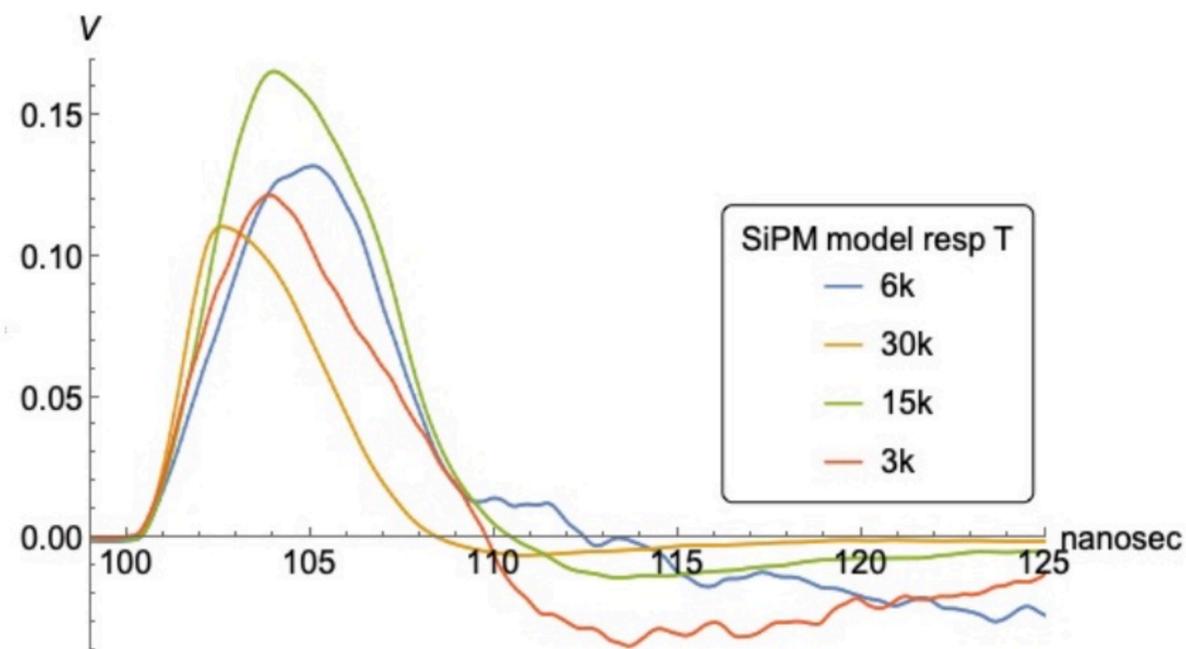
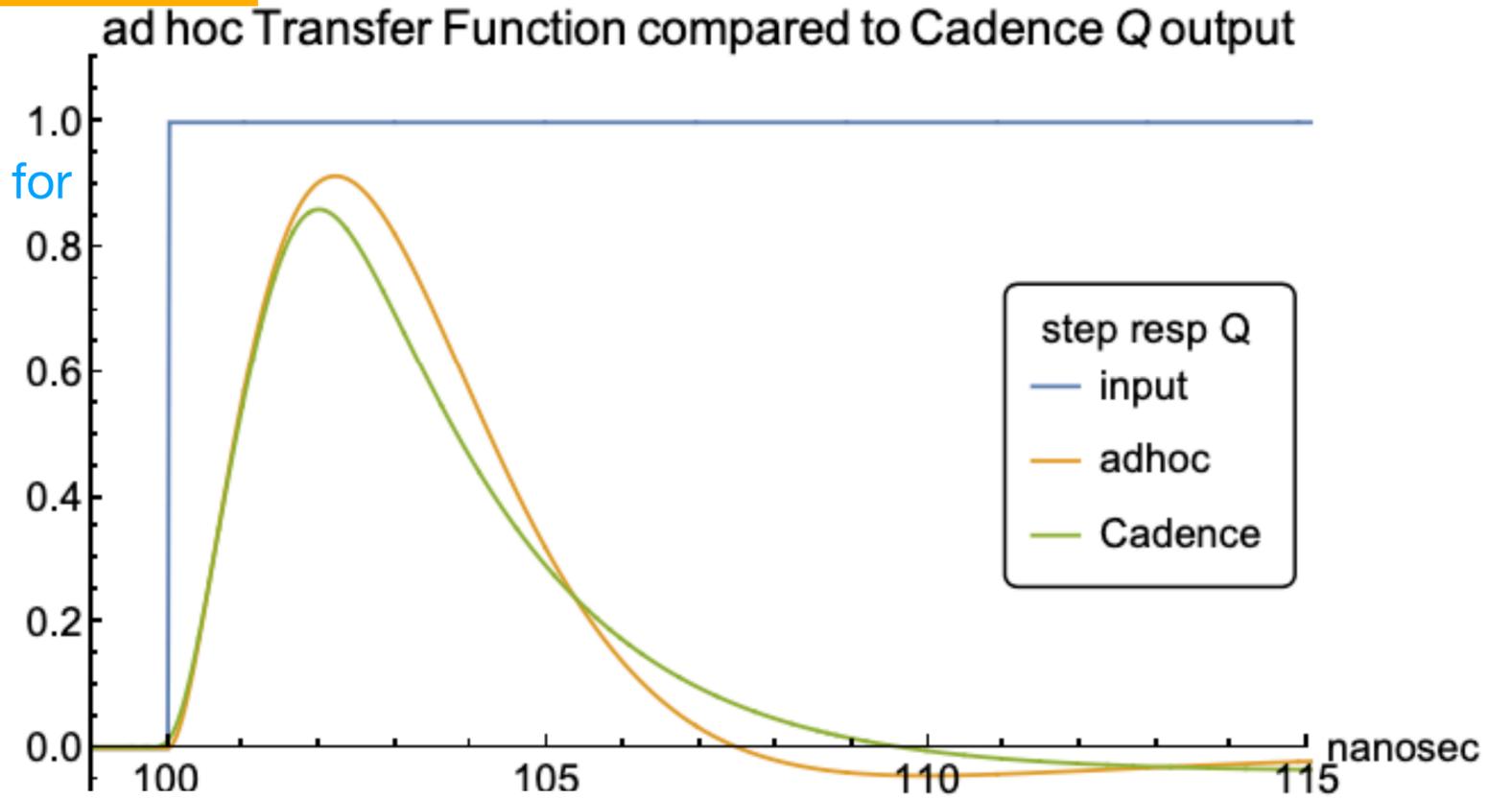
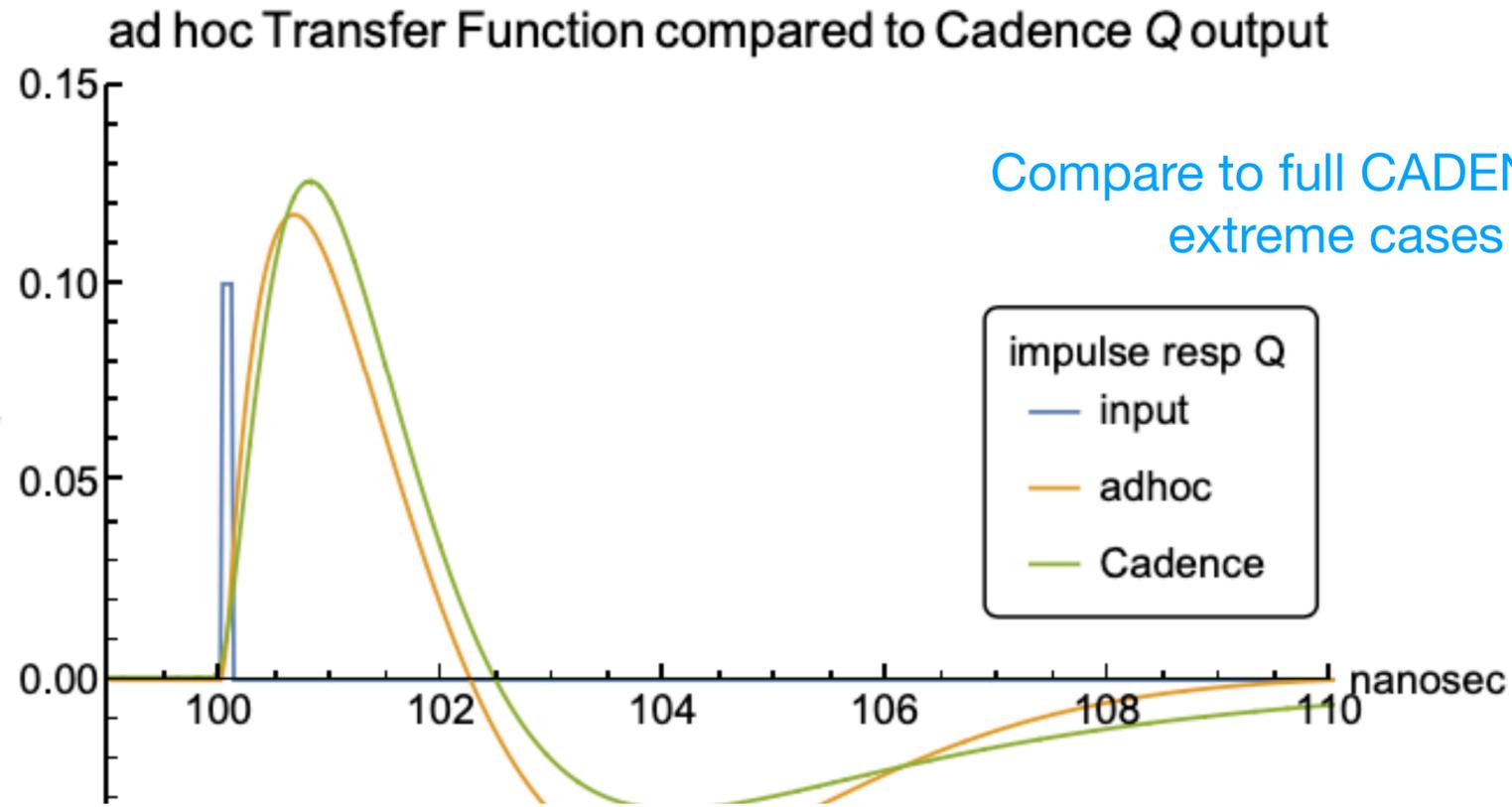
Examples of delay and subtract
for dt= 0.25, 0.5 , 1.0 nanosec



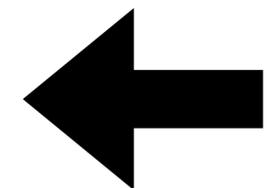
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Probe CADENCE model to get “lightweight” code for xfer Functions

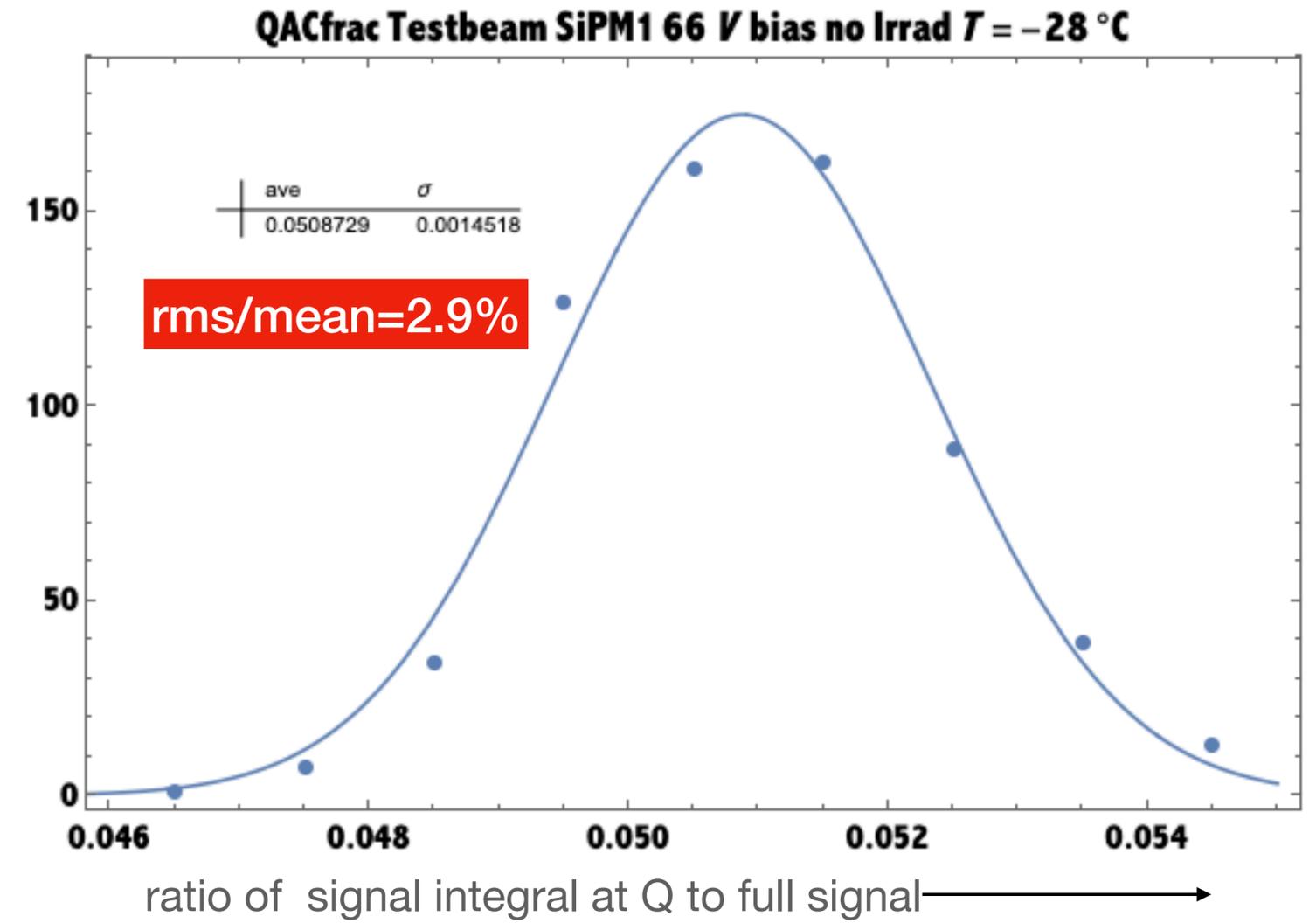
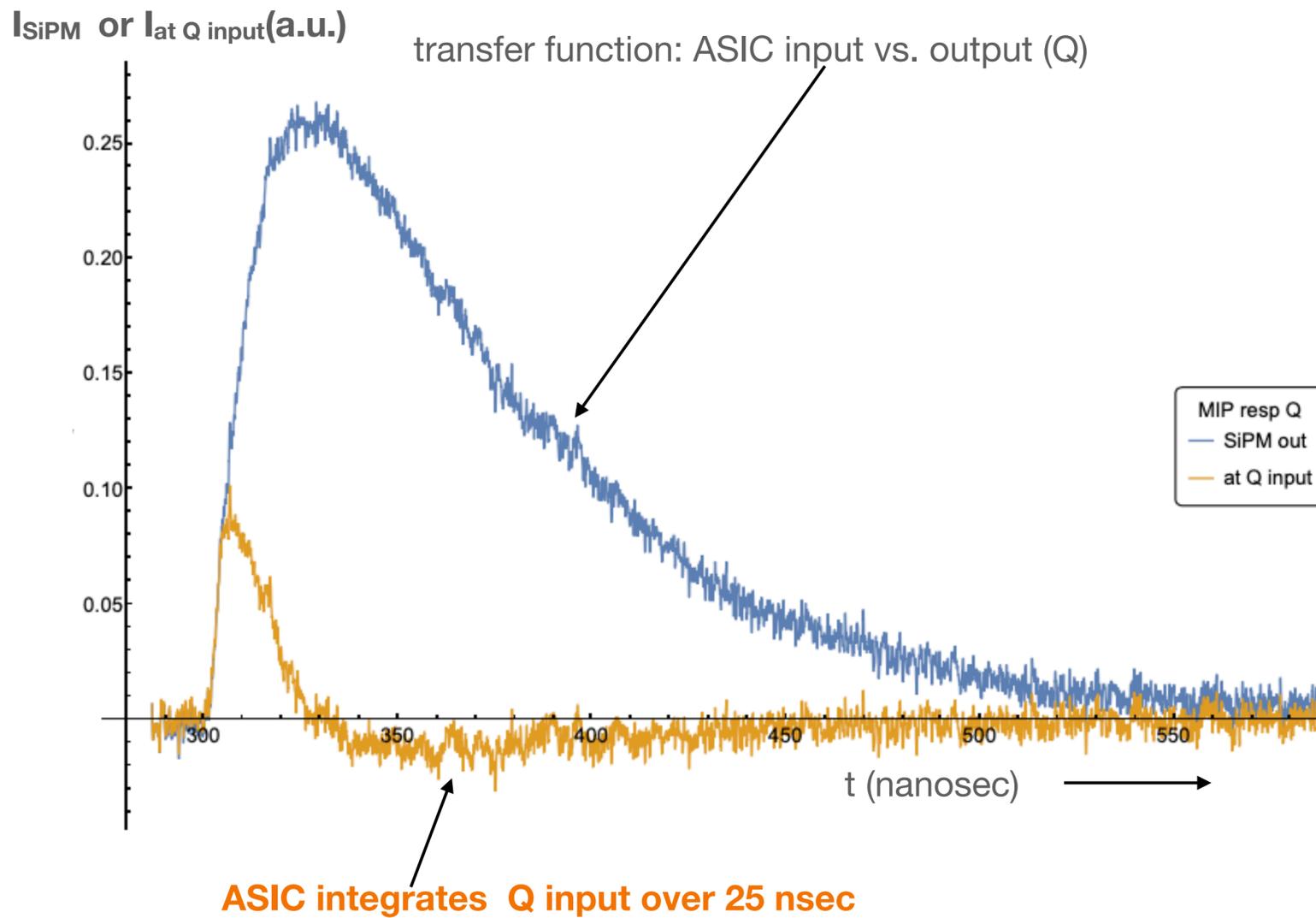
(to anticipate CMS BTL TOFHIR performance in beam)



Probe nodes at Disc inputs to show circuit response linearity



Illustrative Application: How accurately does ASIC capture full Q?

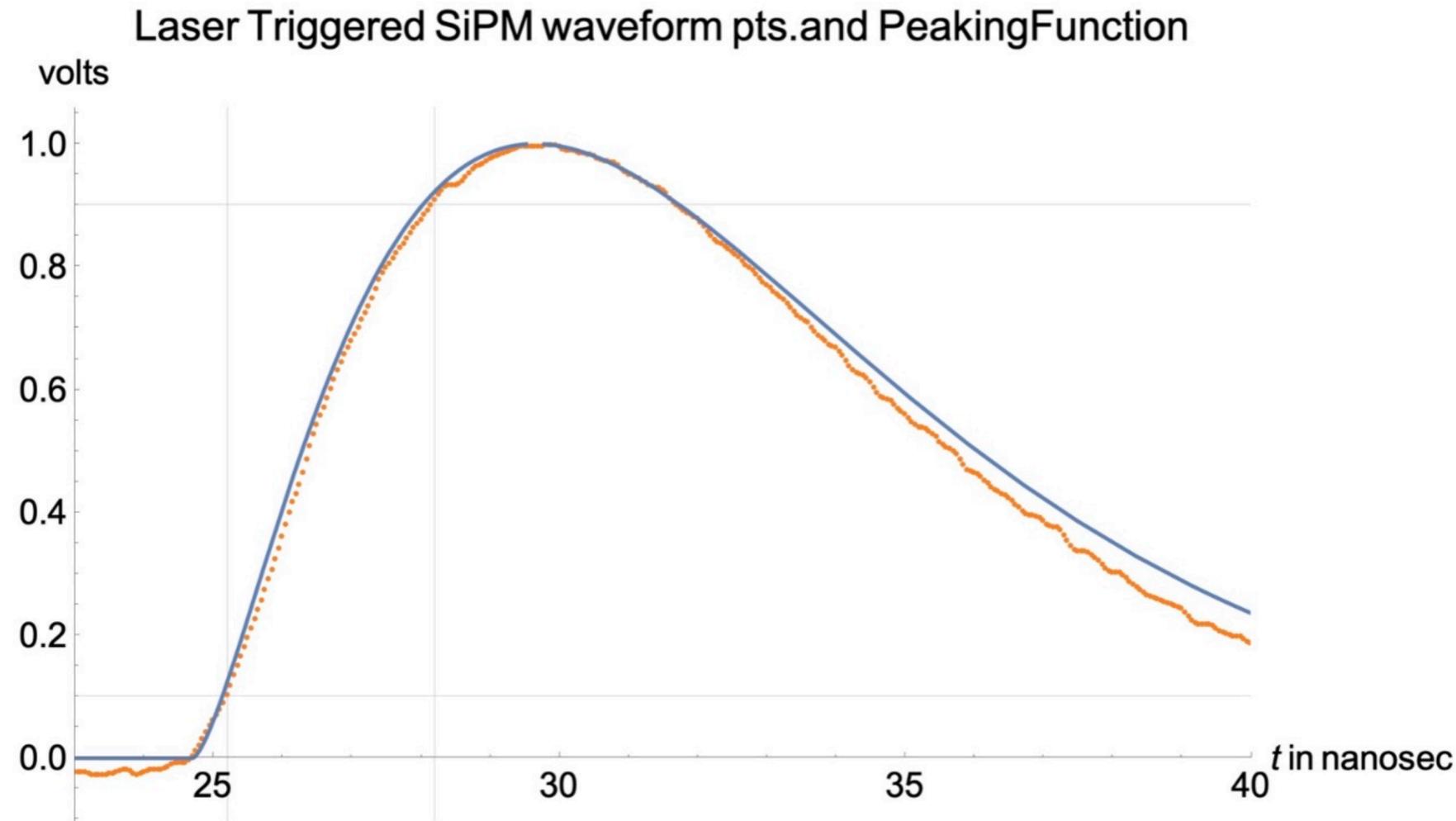


Demonstrates that Q accuracy (for “Amplitude Walk Correction”) of $\sim 5\%$ achieved for a real data set.

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Now illustrate tool for DCR time jitter mitigation.

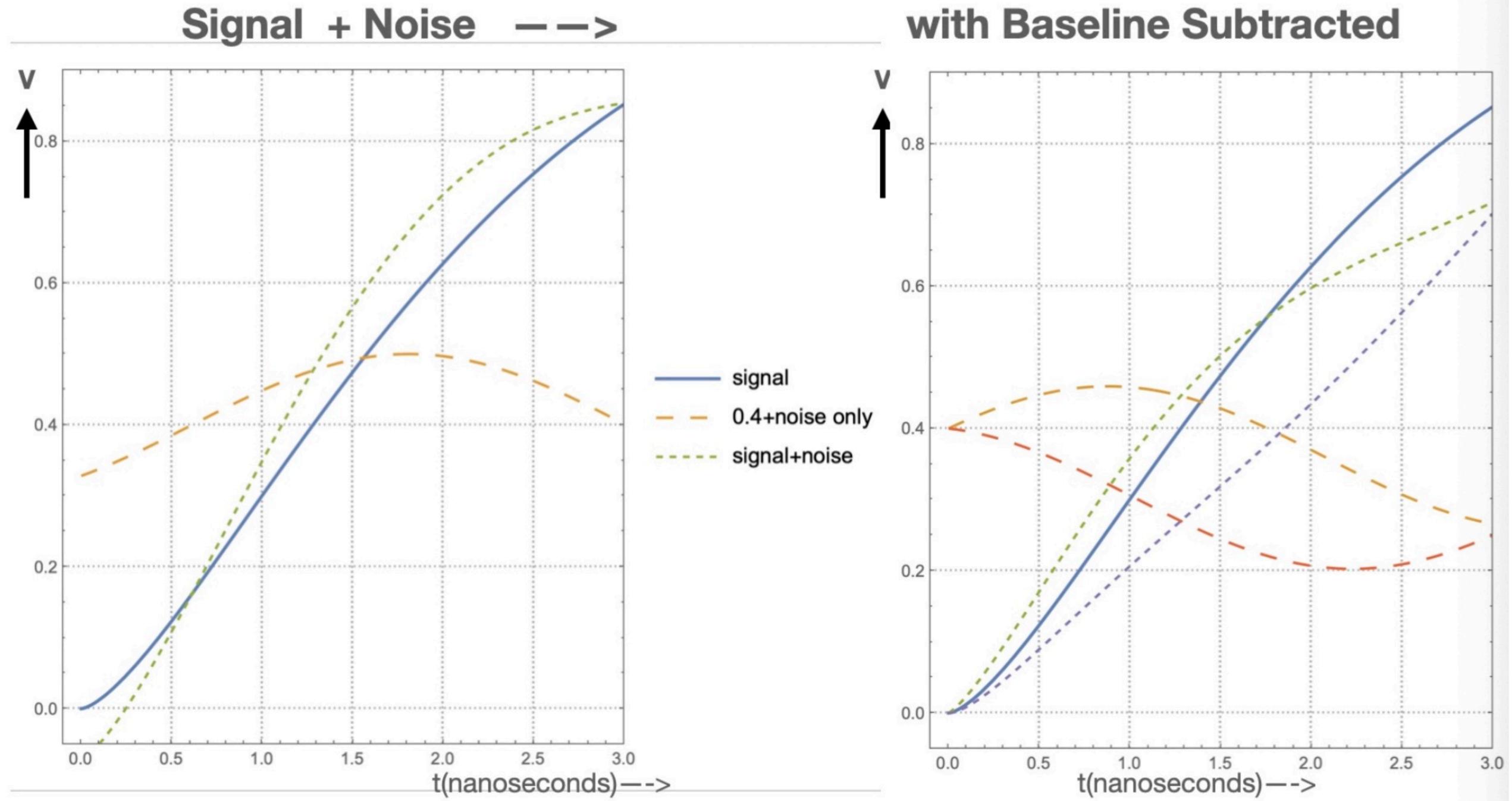
- We will find a timing correction from redundancy of slope and Q.
- Joram Lab laser data from earlier paper w A.Heering: start from models.



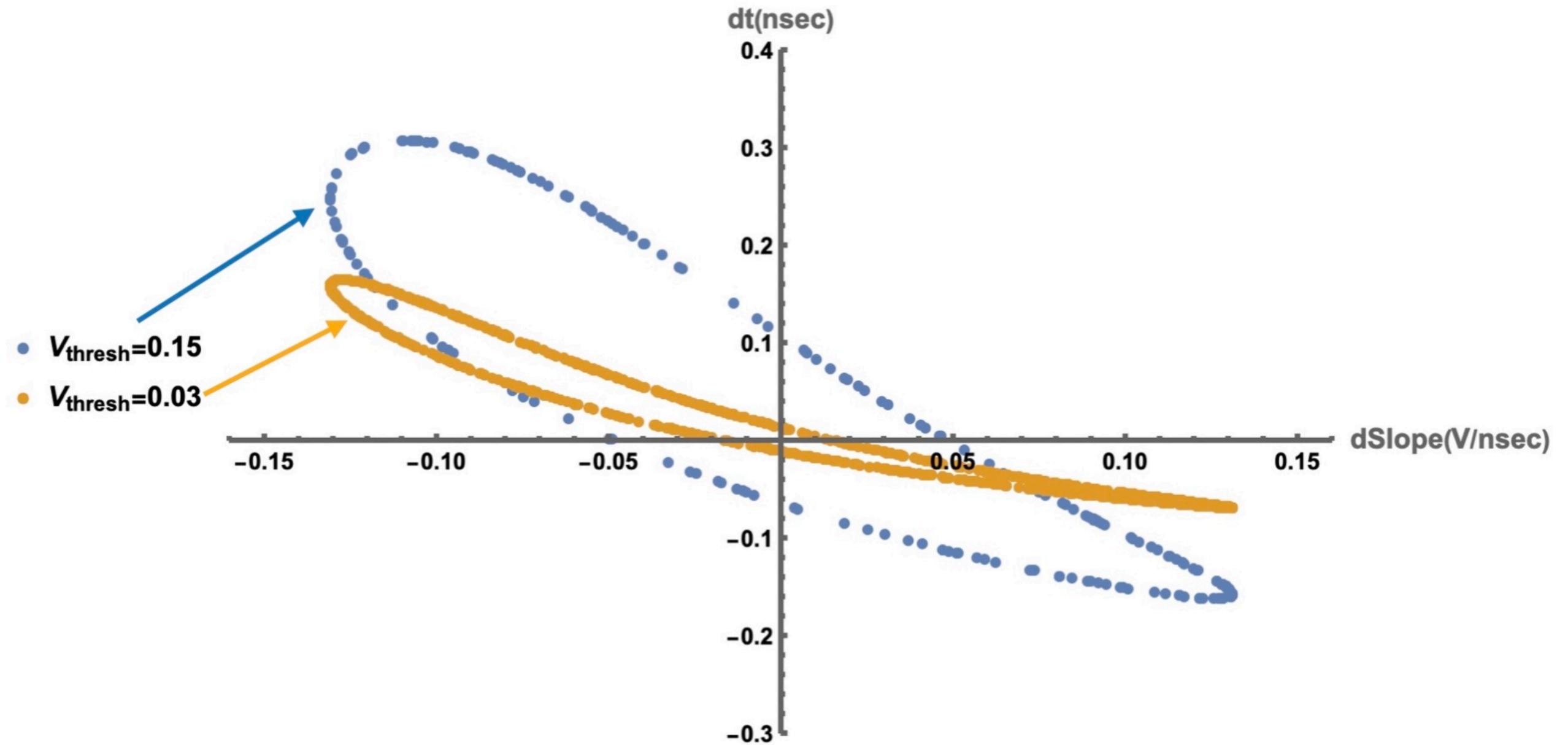
Solid Curve (signal model) —>

$$F[t] = A \times \left(\frac{t - t_0}{\tau}\right)^n \times \text{Exp}\left[-\frac{(t - t_0)}{\tau}\right]$$

Key to dual threshold effectiveness-> baseline subtraction

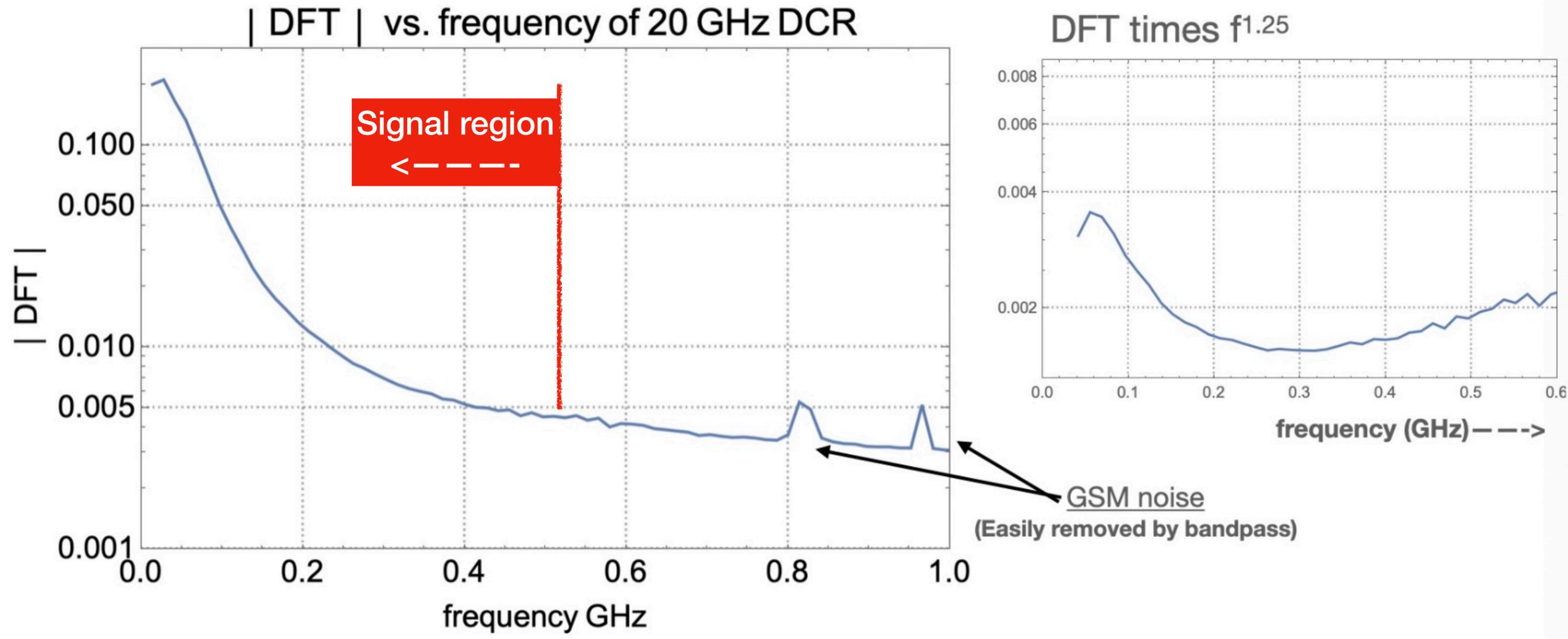


In simple model correlation persists up to high threshold



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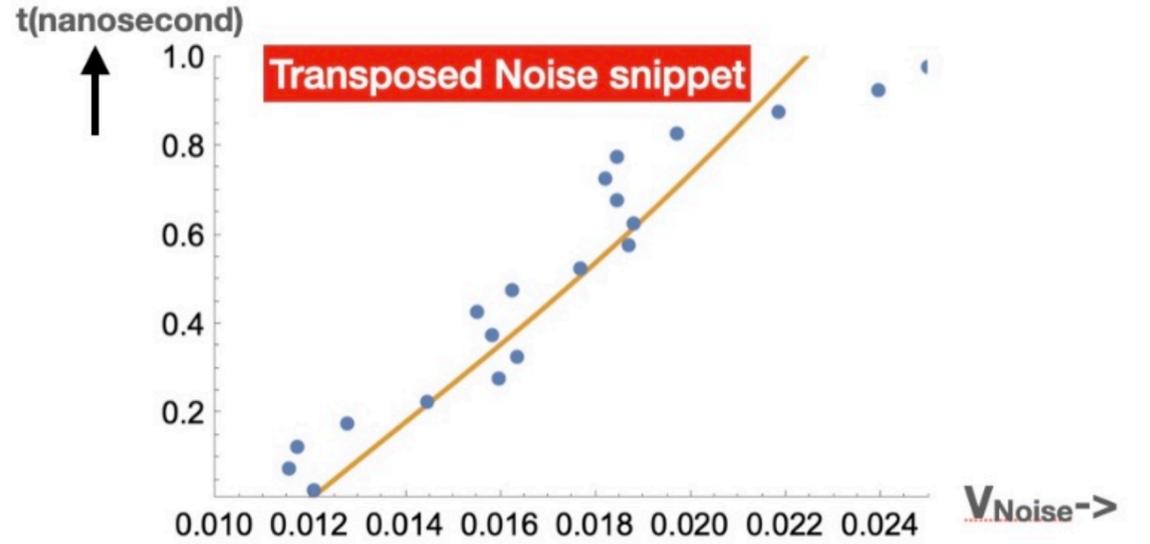
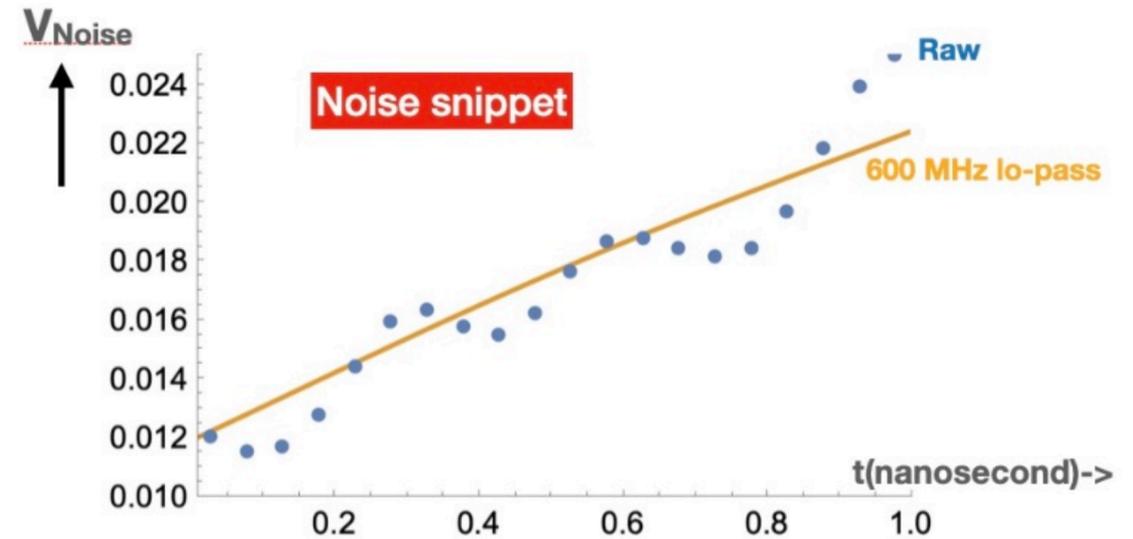
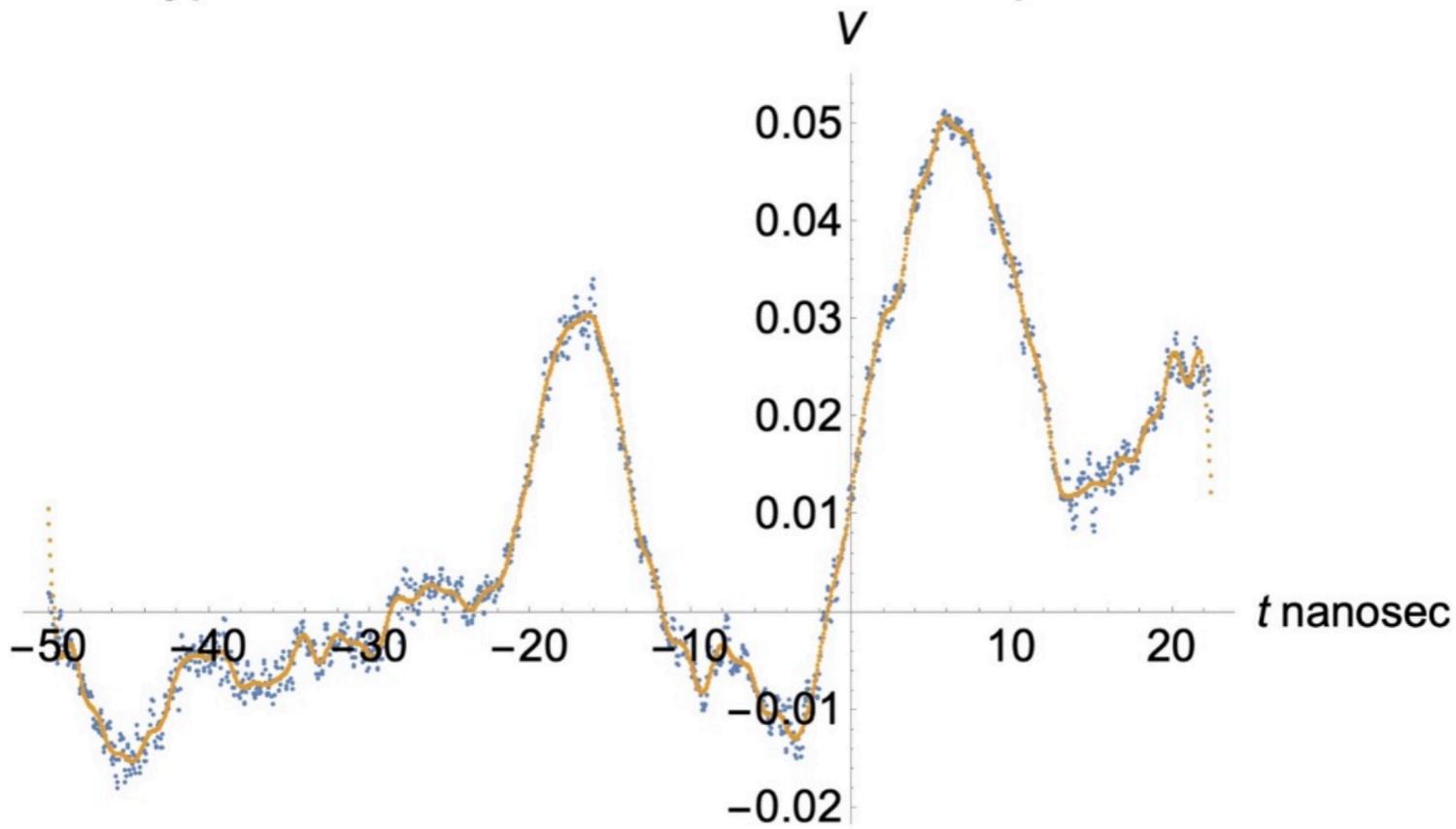
The noise spectrum+ external HF noise (above proper bandpass)



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Even at low power HF noise has a big effect

Typical DCR and after 600 MHz low – pass

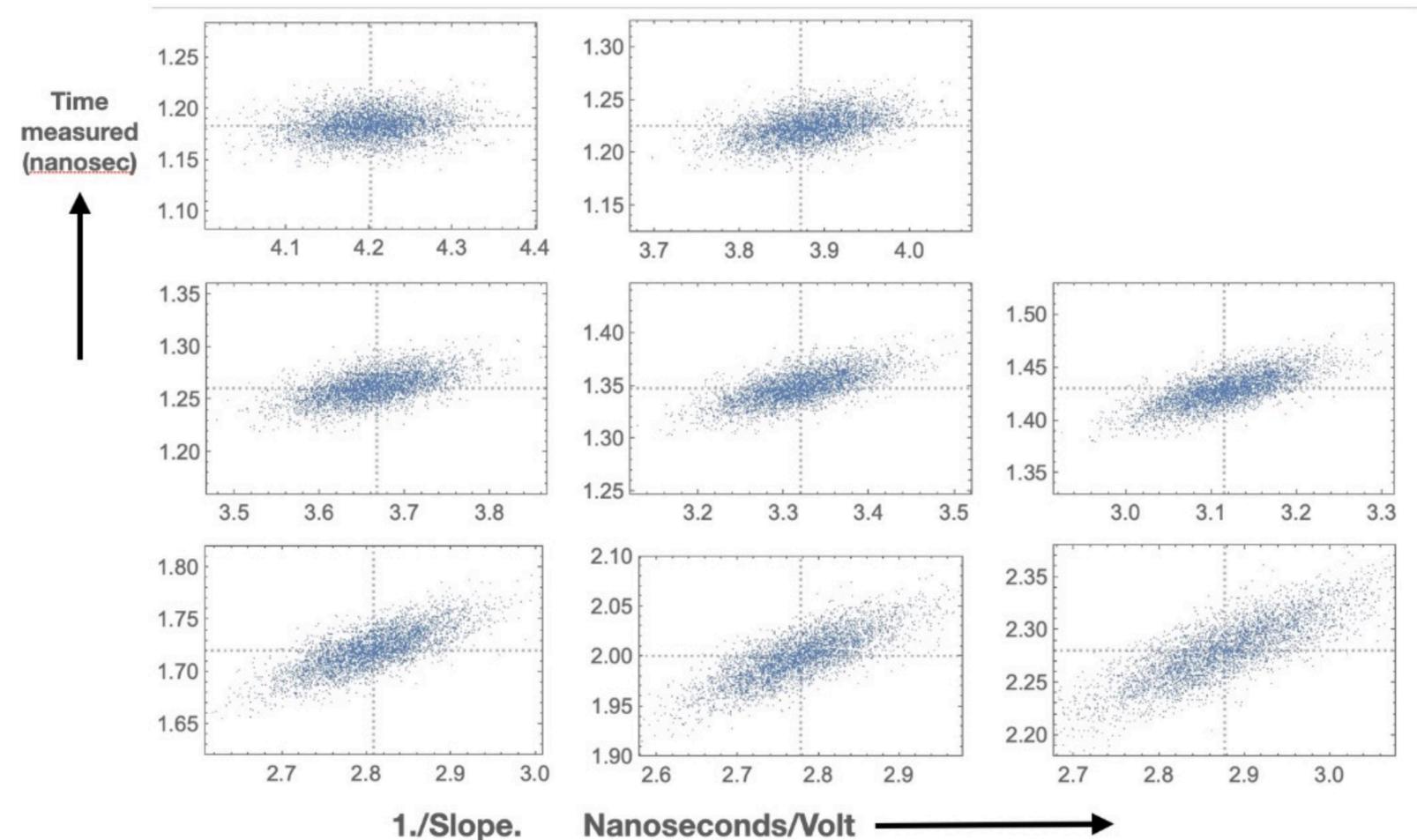
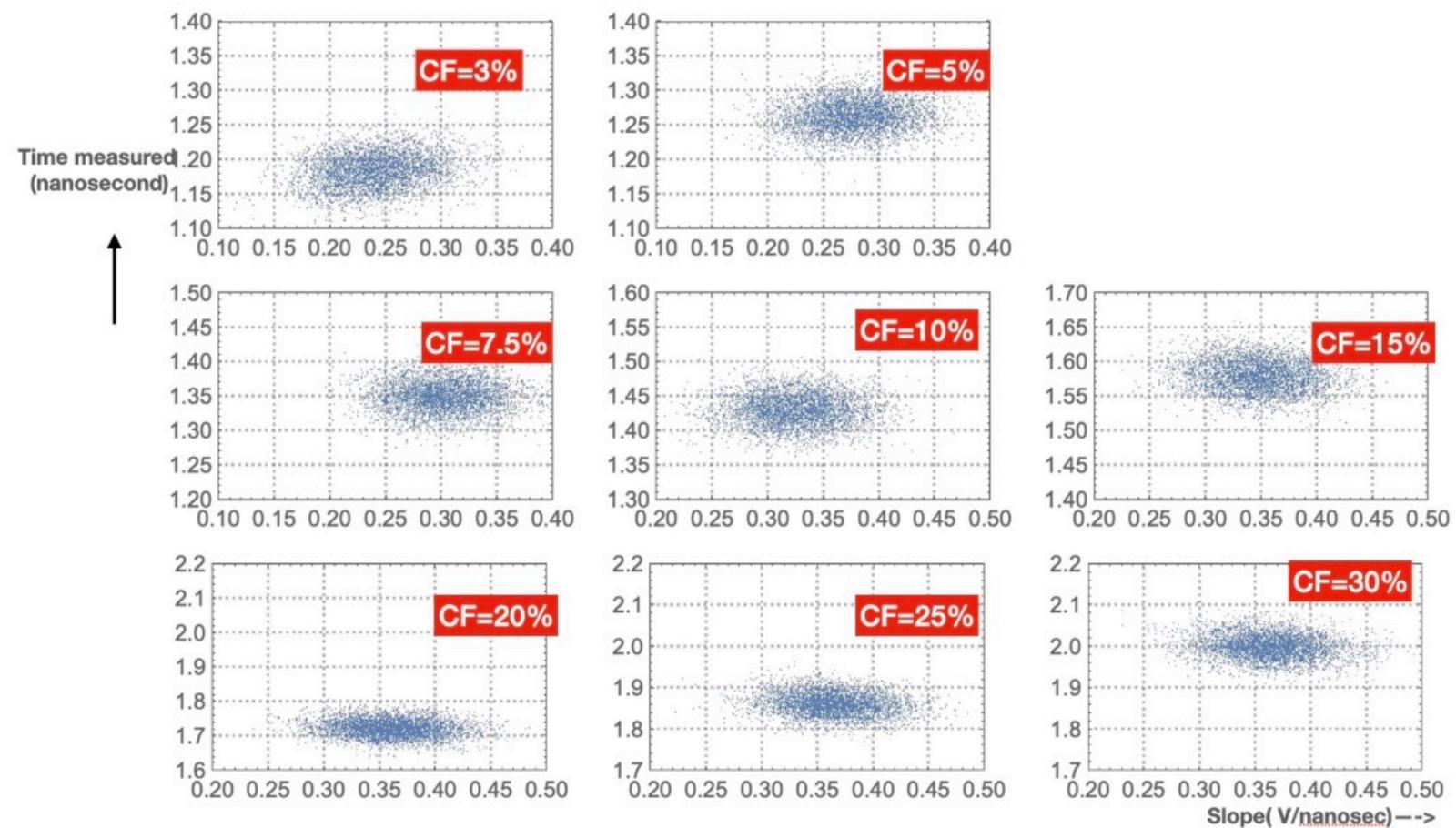


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In our example it would short circuit timing mitigation:

Without 600 MHz low-pass filter

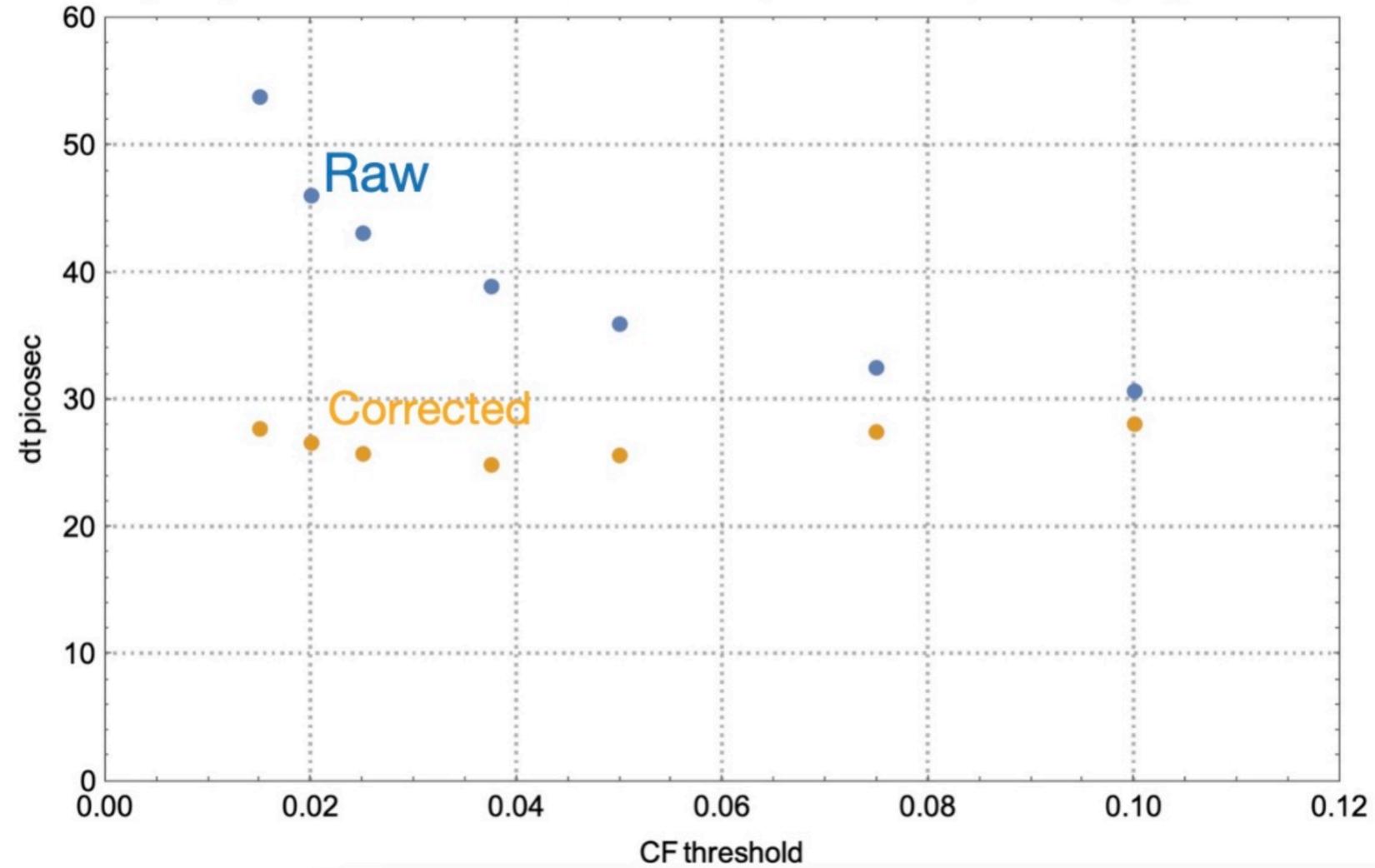
With 600 MHz low-pass filter



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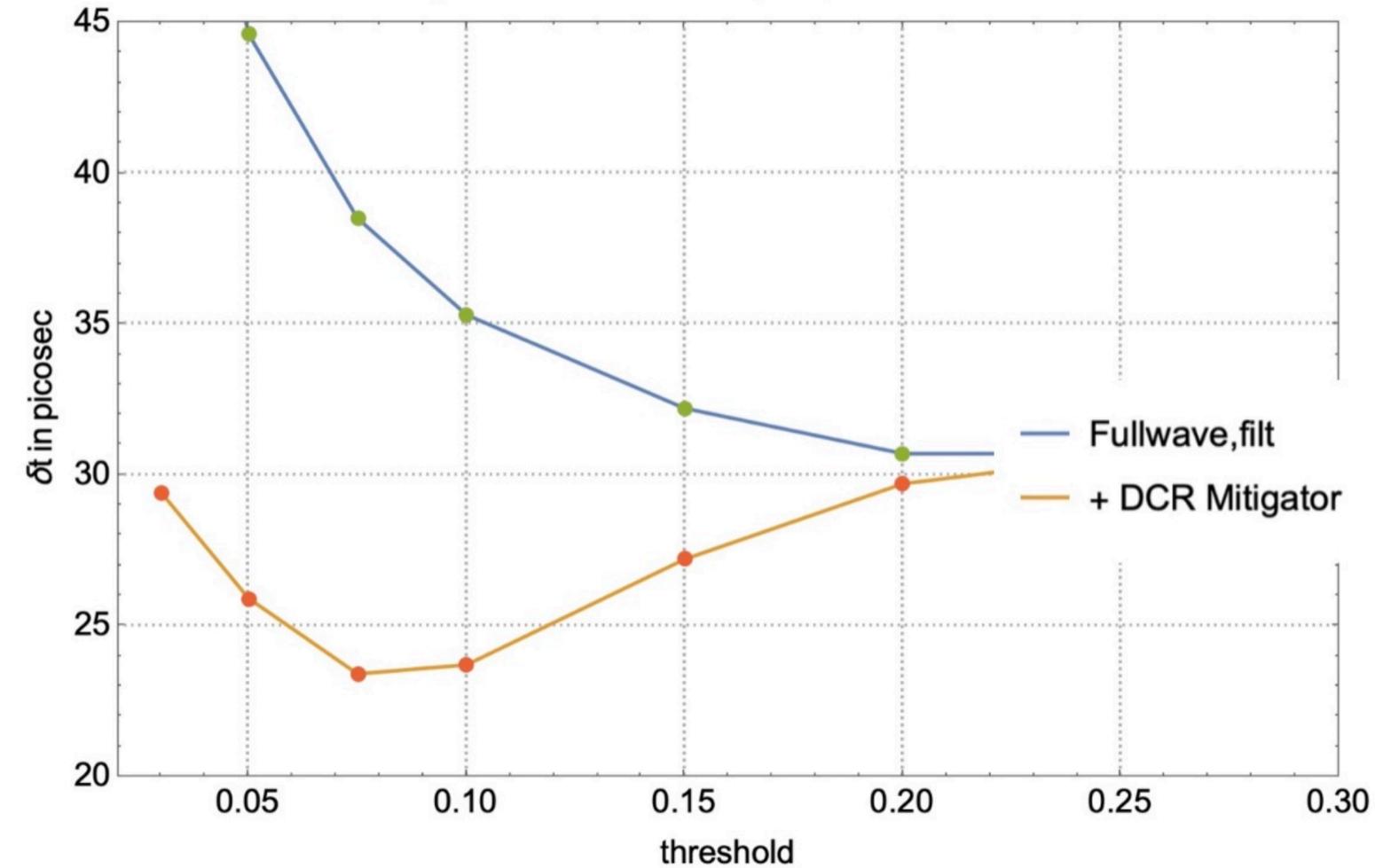
Does Delay Line Shaping (a la TOFHIR) reduce effectiveness? NO

Time jitter picosec before and after correction (290 mV laser) SDL shaping 0.6 nanosec



Model Signal+Real Noise

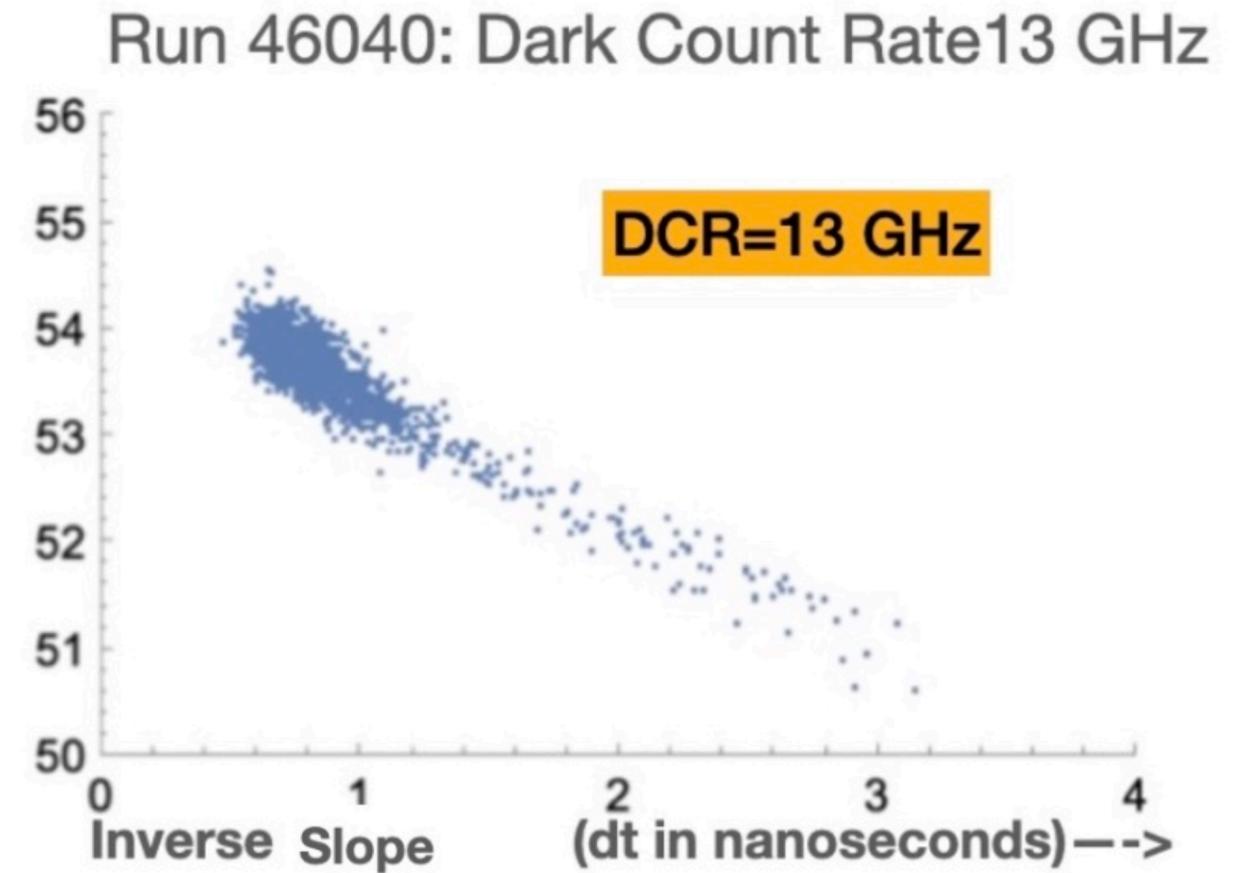
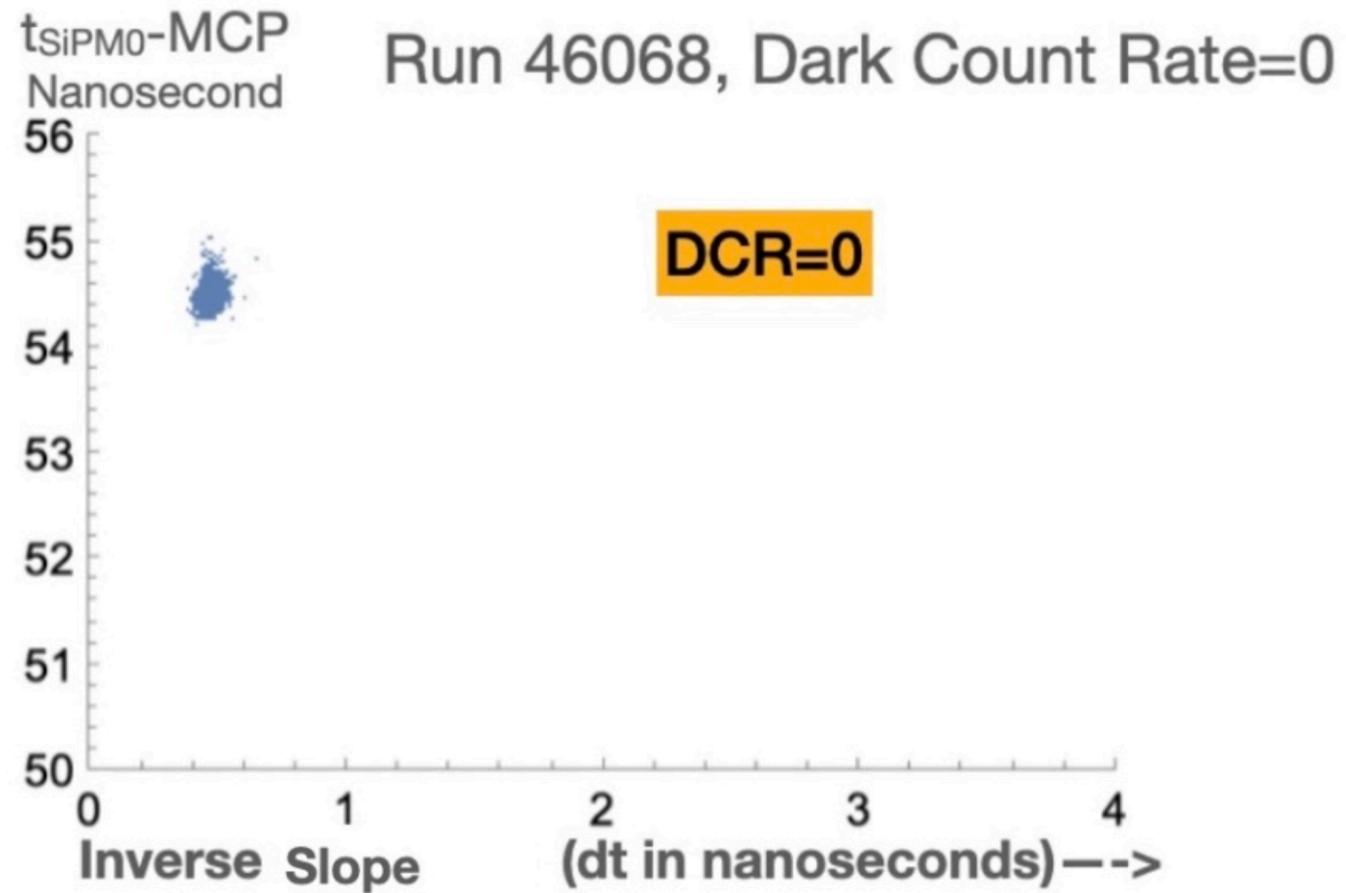
Time jitter vs. threshold (a.u.), DCR = 20 GHz



Full Laser data+Real Noise

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No less effective in LYSO/SiPM FNAL beam data than Laser



As we have seen before.

Role of electronic noise in the workflow (in following-> impact in 2 steps).

Start from the usual steps in the workflow

- 1) record time of threshold crossing (TOFHIR T1)
- 2) Apply a correction to T1 time to give "Time of Arrival (TOA)", using Q.

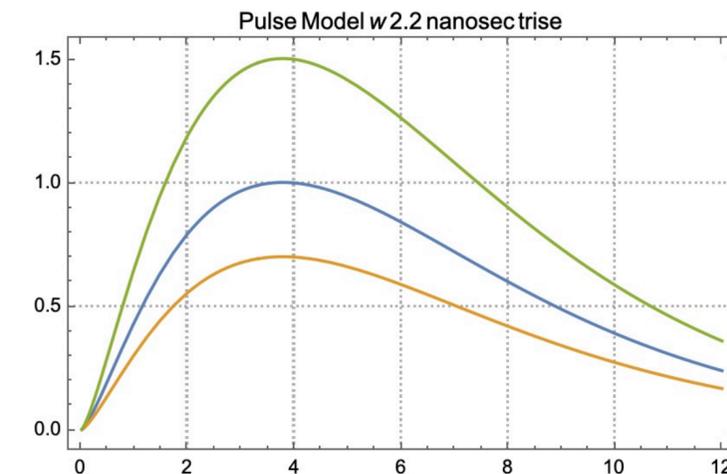
$$\rightarrow T_{\text{ConstantFraction}} = T1 * f[Q]$$

- This "Amplitude Walk Correction" is main correction to the TOA and $f[Q]$ can, typically, just be derived from calibration data.

That is why CF rather than, ie, t_0 .

- Effective 'cause we spec'd Q error to be <5% (and this confirmed in lab).
- We could have, equivalently, used a measurement of $dV^{\text{signal}}/dt|_{@ T1}$ to construct walk correction.

However precision of $dV^{\text{signal}}/dt|_{@ T1}$ was not spec'd or measured (but discussed below).



- 3) at this point note contribution of electronic noise to the TOA. -> enters through usual jitter:

$$dT1 \sim V^{\text{noise}}_{\text{rms}} / (dV^{\text{signal}}/dt|_{@ T1}) \quad (\text{from noise rms})$$

And note that just rms noise that enters- not the noise power spectrum.

Role of electronic noise in the workflow (in following-> impact in 2 steps).

Next we encounter DCR and ask if another correction analogous to “Amplitude walk correction” can be found

4) Using BTL data w. Scope DAQ we find a similar walk correction derived from noise slope

How well can we Measure slope with TOFHIR? Now a clear Incentive!

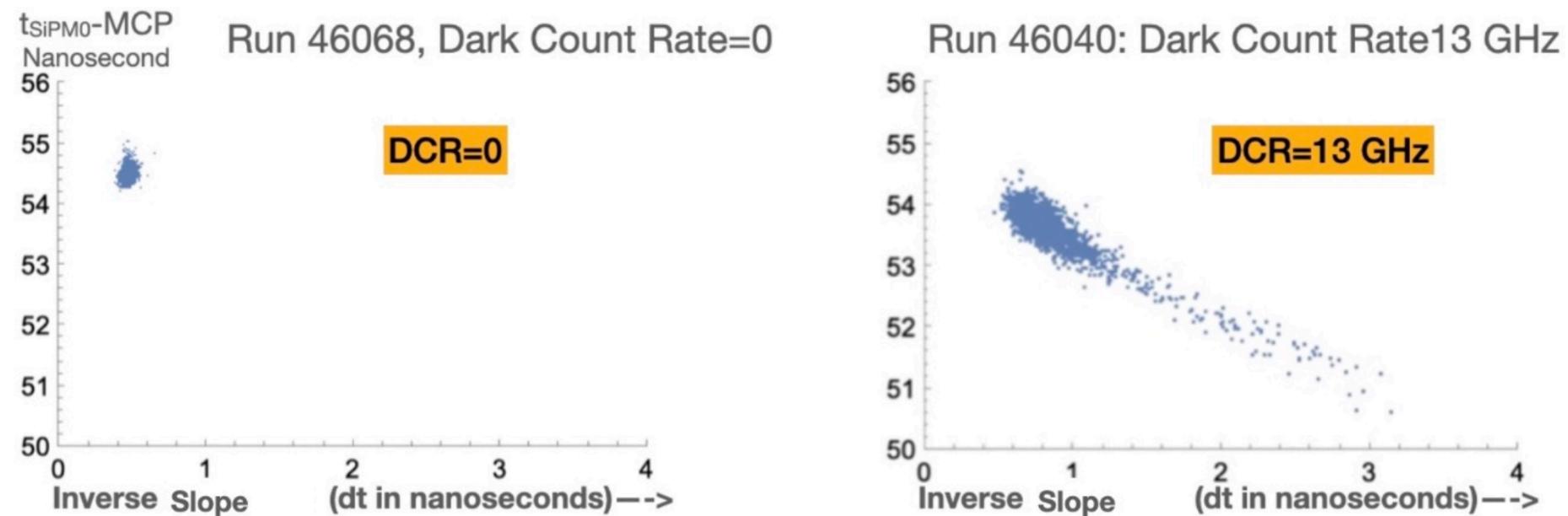


Figure 9. The same analysis was applied to testbeam data of a LYSO/SiPM model detector for the CMS Barrel Timing upgrade [3] in a 120 GeV proton beam at FNAL. The correlation between slope and time shift is seen clearly using highly radiation damaged SiPMs with DCR=13 GHz (right panel) whereas, as expected, time spread and slope spread were insignificant when using undamaged SiPMs (left panel).

- S. White, "Signal processing to reduce dark noise impact in precision timing", Journal of Instrumentation, Volume 18, July 2023, url = <https://dx.doi.org/10.1088/1748-0221/18/07/P07051>

Role of electronic noise in the workflow (in following-> impact in 2 steps).

How does electronic noise enter slope jitter?

4a) for data with given Q expect to see, on average, a signal slope of $\langle dV^{\text{signal}}/dt|_{@ T_1} \rangle$

4b) recall that in TOFHIR2C measurements actually on current but use $V \leftrightarrow I(\mu\text{Amps})$

4c) How does noise enter slope measurement?

$$\text{“Slope”} \sim dV/dt|_{@ T_1} = dV^{\text{signal}}/dt|_{@ T_1} + dV^{\text{noise}}/dt|_{@ T_1}$$

(from noise slope-> frequency content important)



In what follows we will try to derive observed de-correlation in TOFHIR using what is known about TOFIR noise.

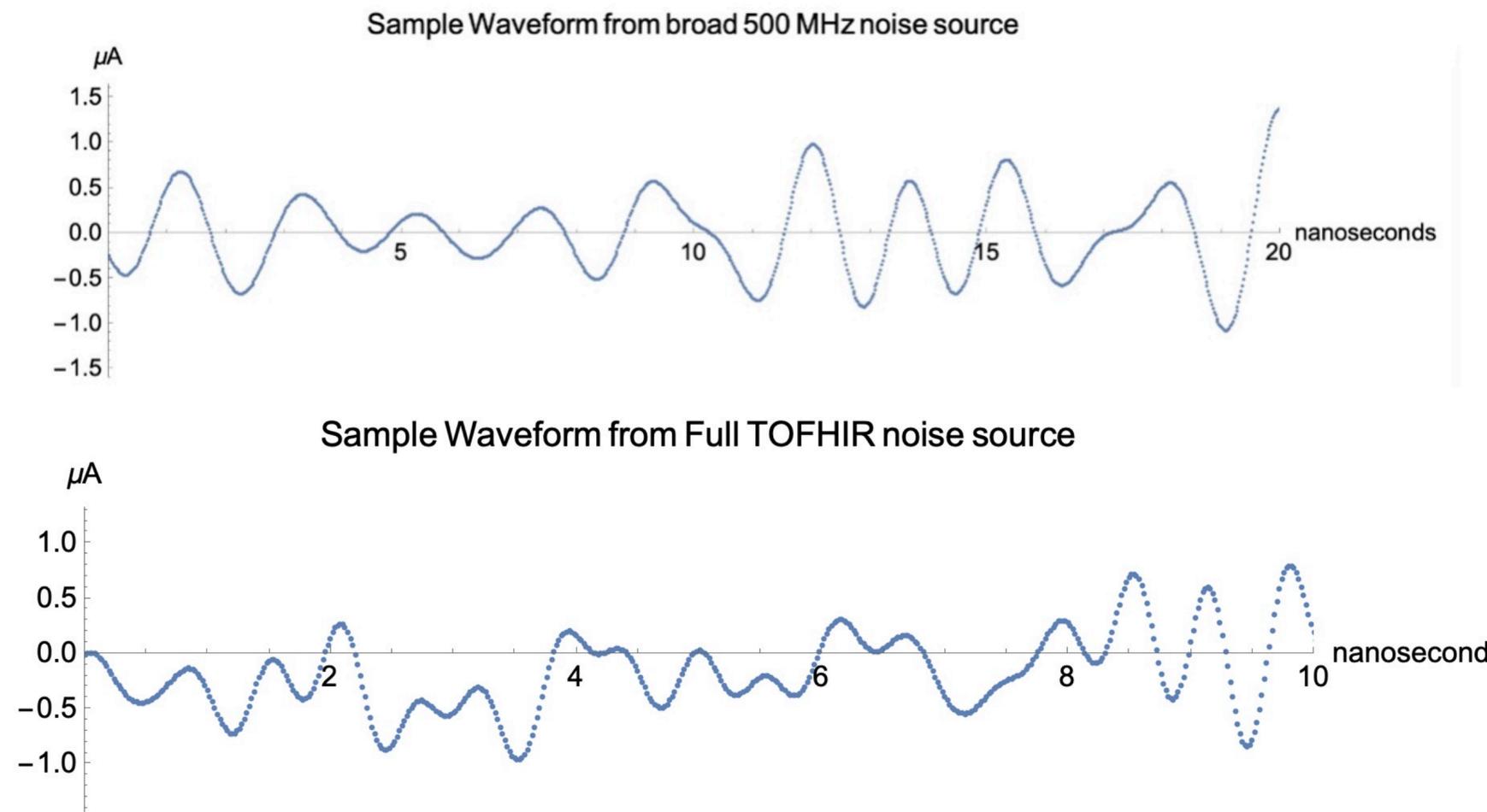
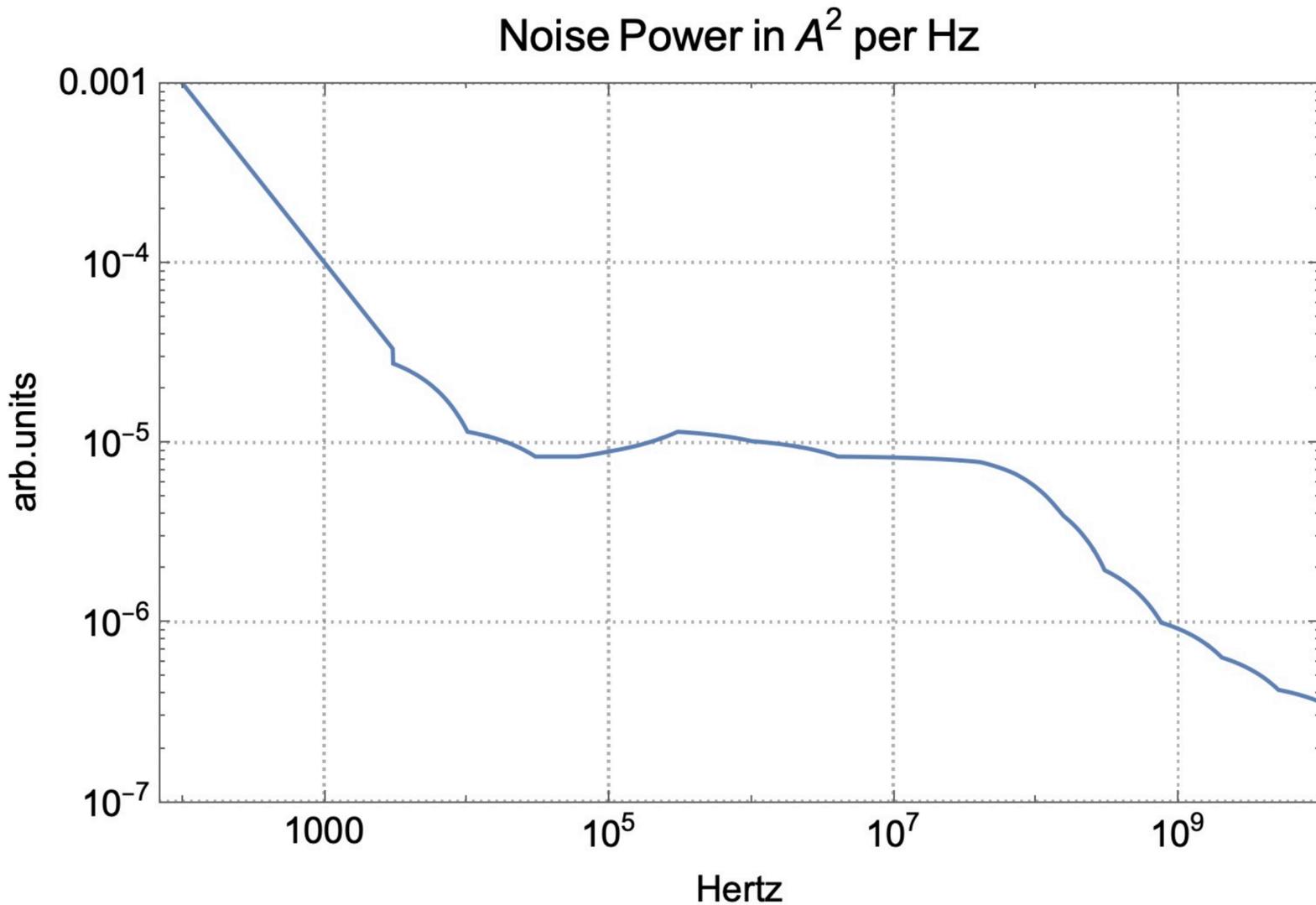
Calculating slope jitter due to noise:

1) Overall (integrated over f) rms noise: various lab measurements -> ~ 0.4 microAmp.
->this provides normalization of power spectrum

2) Power spectrum: from xfer function to T1 discriminator input

Or directly from CADENCE calculation of power spectrum at T1 input

**->Construct random waveforms in time-domain
Using Sqrt[PowerSpectrum] to generate Discrete FT**



Summary

- Various lab and testbeam studies of Digitized waveforms have been a useful complement to TOFHIR simulations with CADENCE and TOFHIR TB/Lab data.
- Potential further improvement in time jitter @high DCR w. TOFHIR 2 thresholds.
- I presented tools to relate its effectiveness to understanding of internal noise.

Sanskrit equivalent of The Riddle of the Sphinx: Riddle contest between a Yaksha and Yudhishtira

Q:What is happening?

A: What is happening is TIME.

What is happening?

What is happening is TIME.

“In this massively deluded
cauldron of a world
where the sun is fire
and the days and nights
fuel that fire
and the months and seasons
the ladle of the cauldron”⁽¹⁵⁾

Time cooks creatures.

THAT's what's happening.

kā ca vārtika?

*asmin mahāmohamaye katāhe
suryāgninā rātri divendhanena
māsartudarvī parighattanena
bhūtāni kālāḥ pacatīti vārta*

अस्मिन् महामोहमये कटाहे सूर्याग्निना रात्रिदिवेन्धनेन ।

मासर्तुदर्वीपरिघट्टनेन भूतानि कालः पचतीति वार्ता ॥ ९९

thanks to Milind Diwan for this reference