# Classification of pulses in the LUX-ZEPLIN dark matter detector.

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# Description of the project

• Rare event observatory with an ultra-low background dual-phase xenon time projection chamber (TPC) designed for particle dark matter searches.

Signals considered in our classification:

- S1 Scintillation signal
- S2 Electroluminescence signals
- SE single electron signals
- Other signals



# Description of the data

1000000 pulses; 20 features

Most relevant:

- **pA:** Total area of summed pod from pulse start to end
- **pH:** Max amplitude of summed pod within pulse
- **pL:** Length of the pulse
- TBA: Ratio of total area of top PMTs vs. total area of bottom PMTs
- aft5: Time at which summed pod reaches 5% of total area
- **pF100:** Fraction of summed pod area in 100ns window at start of pulse relative to total pulse area; window defined from aft5 to 100ns after
- **pF500:** Fraction of summed pod area in 500ns window at start of pulse relative to total pulse area; window defined from aft5 to 500ns after
- **pF5k:** Fraction of summed pod area in 5µs window at start of pulse relative to total pulse area; window defined from aft5 to 5µs after.

# Data plots

To get an idea of how the data behaved, several plot were done:







### **Correlation Matrix before normalization**



# Normalization

Two distinct normalizations were done:

**Quantile Transformer** 

Standard Scaler

# Normalization

Two distinct normalizations were done:

### **Quantile Transformer**

This method transforms the features to follow a uniform or a normal distribution. Therefore, for a given feature, this transformation tends to spread out the most frequent values. It also reduces the impact of (marginal) outliers: this is therefore a robust preprocessing scheme.

Standard Scaler

### **Quantile Transformer**

### Scatter Matrix

**Correlation Matrix** 





### Quantile Transformer (threshold=0,5)

### Scatter Matrix



# Normalization

Two distinct normalizations were done:

Quantile Transformer

### **Standard Scaler**

Standardize features by removing the mean and scaling to unit variance.

Standardization of a dataset is a common requirement for many machine learning estimators: they might behave badly if the individual features do not more or less look like standard normally distributed data (e.g. Gaussian with 0 mean and unit variance).

### **Standard Scaler**

### **Correlation Matrix**



### Scattter Matrix



### Standard Scaler (threshold=5,5)

**Scatter Matrix** 



**Correlation Matrix** 



# Supervised learning

### **Random Forest Model**

Results after the classification:

		precision	recall	fl-score	support
	Θ	0.89	0.83	0.86	9191
	1	0.86	0.91	0.88	10615
	2	1.00	1.00	1.00	45858
	3	1.00	1.00	1.00	134336
accur	racy			0.99	200000
macro	avg	0.94	0.93	0.93	200000
weighted	avg	0.99	0.99	0.99	200000

Θ	1	2	3
7628	1546	0	17
955	9617	30	13
Θ	Θ	45837	21
4	0	39	134293
	0 7628 955 0 4	0 1 7628 1546 955 9617 0 0 4 0	0 1 2 7628 1546 0 955 9617 30 0 0 45837 4 0 39

# Supervised learning

### Neural Network

### Results after the classification:

	precision	recall	f1-score	support
0	0.70	0.49	0.57	9191
1	0.66	0.81	0.73	10615
2	0.93	0.92	0.92	45858
3	0.97	0.97	0.97	134336
accuracy			0.93	200000
macro avg	0.81	0.80	0.80	200000
weighted avg	0.93	0.93	0.93	200000

Predicted Class Actual Class	0	1	2	3
0	8033	1102	0	56
1	3815	6712	77	11
2	0	0	45814	44
3	5	0	51	134280

# **Unsupervised learning**

### **Gaussian Mixture Model**

A Gaussian mixture model is a probabilistic model that assumes all the data points are generated from a mixture of a finite number of Gaussian distributions with unknown parameters.

# Clustering of the data











	0	1	2	3
0	0.0	0.0	0.0	6 <mark>43</mark> 337.0
1	5. <mark>0</mark>	36536.0	0.0	0.0
2	1.0	0.0	0.0	0.0
3	0.0	67.0	34 <mark>1</mark> 49.0	27030.0
4	1.0	0.0	0.0	0.0
5	45576.0	0.0	0.0	0.0
6	547.0	16495.0	1.0	0.0
7	0.0	0.0	196251.0	0.0
8	1.0	0.0	0.0	0.0
9	3.0	0.0	0.0	0.0

# Thank you!