



LABORATÓRIO DE INSTRUMENTAÇÃO  
E FÍSICA EXPERIMENTAL DE PARTÍCULAS  
*partículas e tecnologia*

# Data challenge

Data Science School 2022, Coimbra

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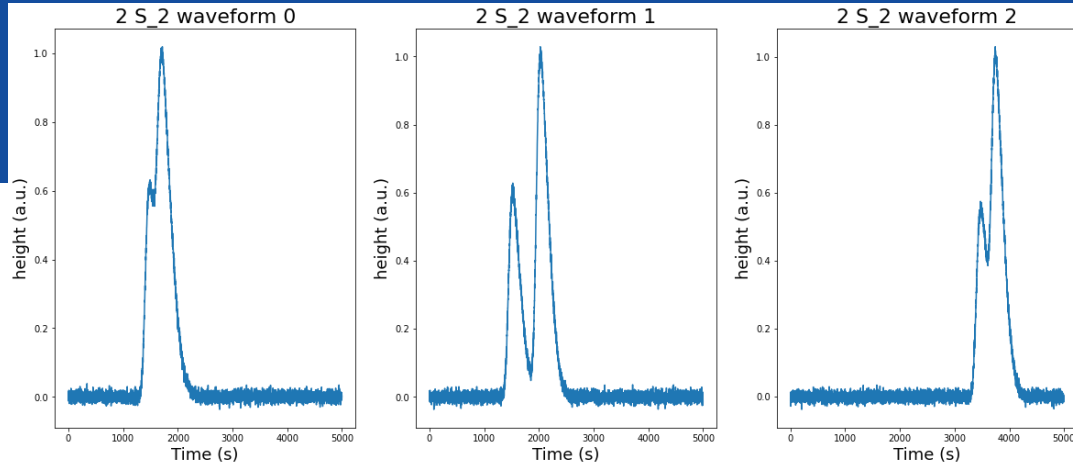


# Outline/Approach

1. Data analysis
2. Data treatment
3. Basic model assembly
  - 3.1. Layers
  - 3.2. Initial tests
4. Optimizing the model
5. Testing on 1S2 waveforms
6. 1S2 and 2S2 distinction

# 1. Data analysis

Check for data format and verify the waveform expected



Input 2S2 waveforms: (20000, 5000)  
Output 2S2 d: (20000,)  
# waveforms: 20000  
# points/waveform: 5000

## 2. Data treatment

Divide into train and validation/'test' batches

```
X_train, X_test, y_train, y_test = train_test_split(input2S2_data, output2S2_data, test_size=0.2, random_state=0)
```

```
Number of waveforms for training: 16000  
Number of points/waveform for training: 5000  
Number of waveforms for test: 4000  
Number of points/waveform for test: 5000
```

## 2. Data treatment

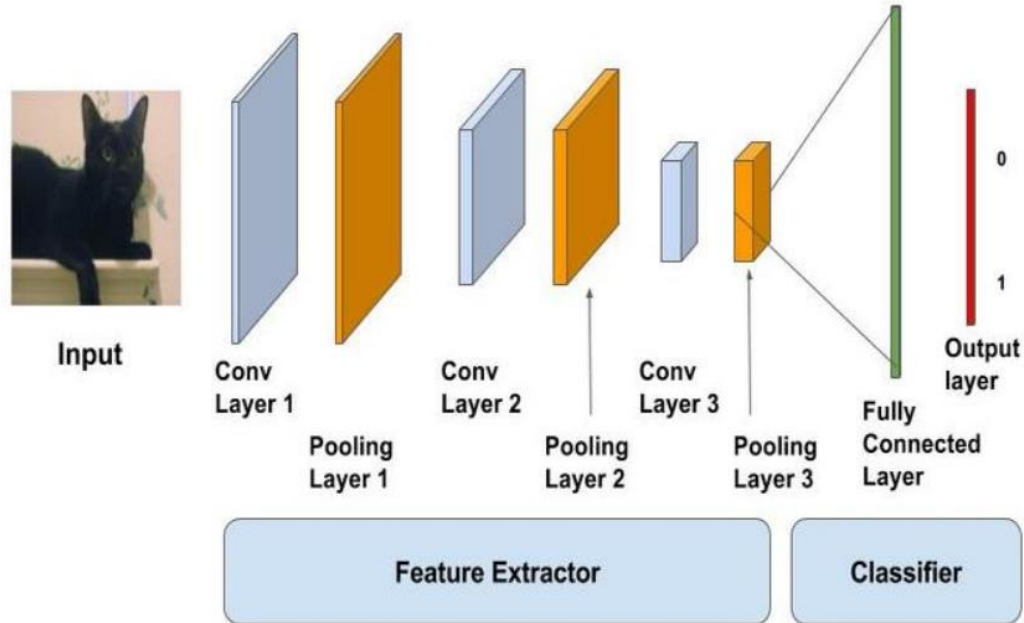
Normalized input data  $X$

$$X = \frac{X - \min(X)}{\max(X) - \min(X)}$$

# 3. Basic model assembly

Stacking of convolutional, pooling, FCL and output layers

# Convolutional neural network



# Convolutional neural network

## 1D Convolution layer

- Receives input with shape (# of waveforms, # timesteps, # 'features')

```
X_train3 = X_train.reshape(-1, n_points, 1)
print('X_train after reformatting: ', np.shape(X_train3))
X_test3 = X_test.reshape(-1, n_points, 1)
print('X_test after reformatting: ', np.shape(X_test3))
```

```
X_train after reformatting: (16000, 5000, 1)
```

```
X_test after reformatting: (4000, 5000, 1)
```



# Convolutional neural network

## 1D Convolution layer

- Characterized by number of filters it must use to extrapolate features, kernel size and stride. For smaller feature 'maps':
  - > Greater kernel size
  - > Greater stride
  - > More convolutional layers

```
#adding convolutional layer  
model.add(Conv1D(32,3,1,activation='relu',input_shape = [n_train_points, 1]))
```

- Started with 'standard' values

# Convolutional neural network

## Pooling layer

```
model.add(MaxPool1D(16))
```

## Fully connected layer

```
model.add(Flatten())  
model.add(Dense(100,activation='relu'))
```

## Output layer

```
model.add(Dense(1,activation='sigmoid'))
```

# Regression model evaluation

```
import keras.backend as K

def my_acc(y_true, y_pred):
    return K.mean(K.equal(K.round(y_true*10), K.round(y_pred*10)))
```

```
optimizer = RMSprop(learning_rate=0.001)
```

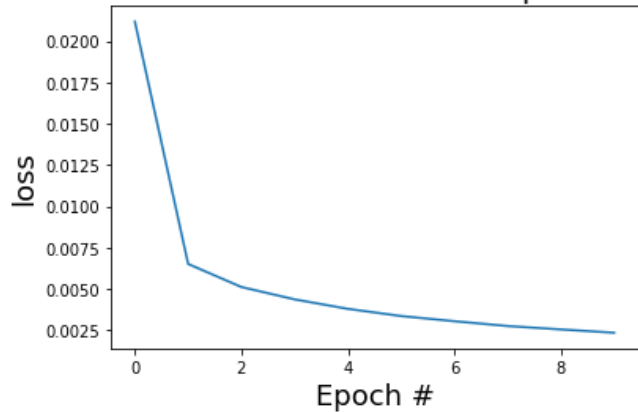
```
model.compile(optimizer, loss='mean_squared_error', metrics = [my_acc])
```

# Initial runs

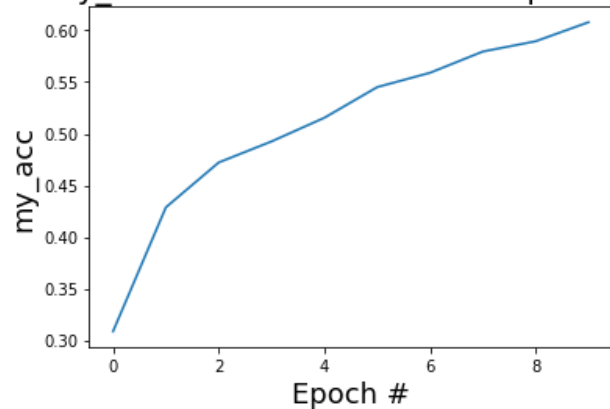
```
Epoch 1/10
125/125 [=====] - 38s 294ms/step - loss: 0.0025 - my_acc: 0.6159 - val_loss: 0.0034 - val_my_acc: 0.5439
Epoch 2/10
125/125 [=====] - 36s 288ms/step - loss: 0.0022 - my_acc: 0.6259 - val_loss: 0.0022 - val_my_acc: 0.6267
Epoch 3/10
125/125 [=====] - 37s 296ms/step - loss: 0.0020 - my_acc: 0.6489 - val_loss: 0.0022 - val_my_acc: 0.5928
Epoch 4/10
125/125 [=====] - 37s 299ms/step - loss: 0.0019 - my_acc: 0.6491 - val_loss: 0.0031 - val_my_acc: 0.5640
Epoch 5/10
125/125 [=====] - 37s 298ms/step - loss: 0.0018 - my_acc: 0.6544 - val_loss: 0.0019 - val_my_acc: 0.6609
Epoch 6/10
125/125 [=====] - 35s 284ms/step - loss: 0.0017 - my_acc: 0.6731 - val_loss: 0.0011 - val_my_acc: 0.7324
Epoch 7/10
125/125 [=====] - 36s 289ms/step - loss: 0.0016 - my_acc: 0.6734 - val_loss: 0.0012 - val_my_acc: 0.7212
Epoch 8/10
125/125 [=====] - 37s 296ms/step - loss: 0.0016 - my_acc: 0.6826 - val_loss: 0.0010 - val_my_acc: 0.7393
Epoch 9/10
125/125 [=====] - 35s 277ms/step - loss: 0.0015 - my_acc: 0.6835 - val_loss: 0.0014 - val_my_acc: 0.6816
Epoch 10/10
125/125 [=====] - 35s 283ms/step - loss: 0.0014 - my_acc: 0.6886 - val_loss: 9.8781e-04 - val_my_acc: 0.7361
```

# Initial runs

loss evolution with Adam optimizer



my\_acc evolution with Adam optimizer



# Initial runs

```
# ----- Check the performance of the model
```

```
score = model.evaluate(X_test3, y_test, verbose=1)  
print('Test loss:', score[0])
```

```
125/125 [=====] - 4s 31ms/step - loss: 9.8781e-04 - my_acc: 0.7387  
Test loss: 0.000987810781225562
```

# Initial runs

```
[[0.9295618 ]  
 [0.13522542]  
 [0.80563235]
```

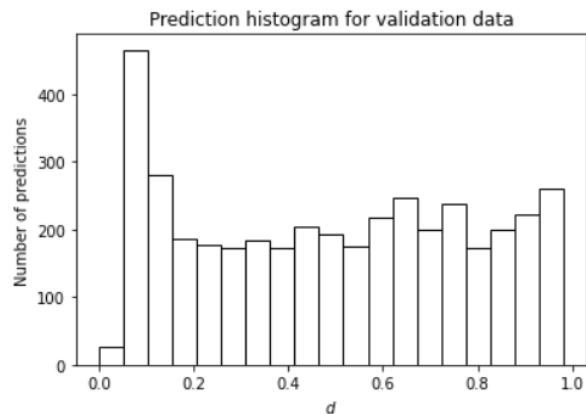
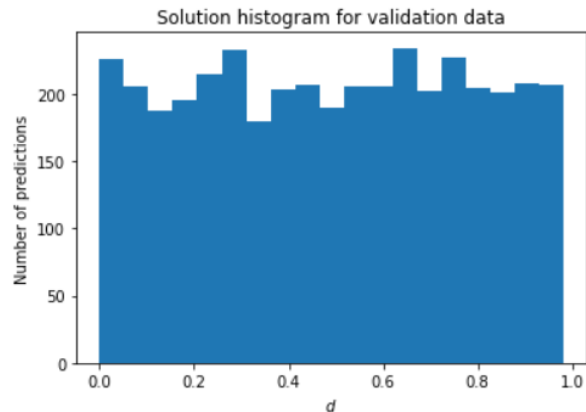
...

```
[0.72264767]  
 [0.06762588]  
 [0.76344526]]
```

```
[[0.97   ]  
 [0.2225 ]  
 [0.80875]
```

...

```
[0.71625]  
 [0.0475 ]  
 [0.7525 ]]
```

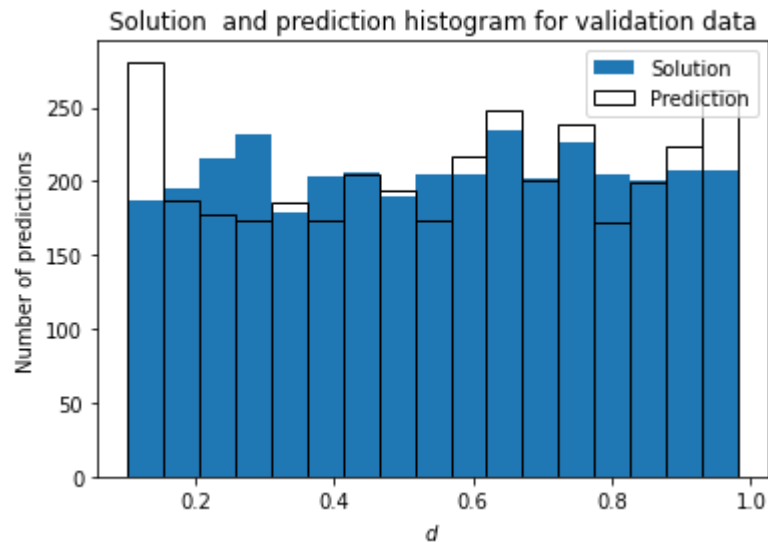


# Initial runs

```
[[0.9295618 ]  
 [0.13522542]  
 [0.80563235]  
 ...  
 [0.72264767]  
 [0.06762588]  
 [0.76344526]]
```

```
[[0.97   ]  
 [0.2225 ]  
 [0.80875]  
 ...  
 [0.71625]  
 [0.0475 ]  
 [0.7525  ]]
```

## Zooming in





## 4. Optimizing the model

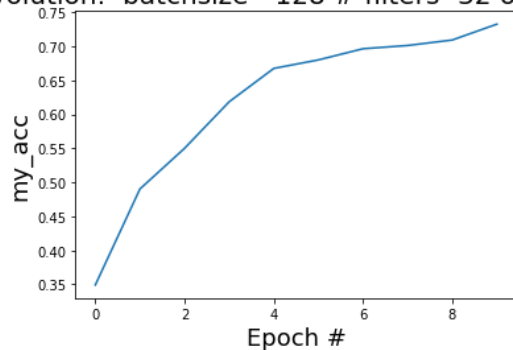
## 2+D Grid search

- Experimented different:
  - Number of filters on convolution layer
  - Optimizers

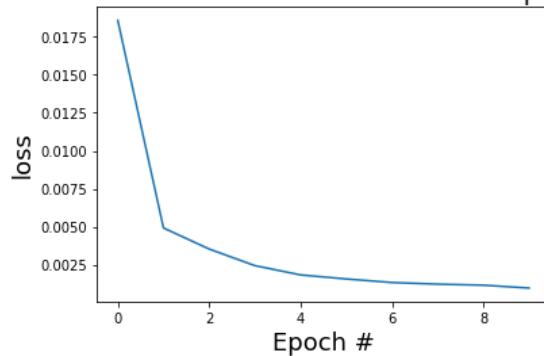
```
def Optimize_param(X_train, y_train, X_test, y_test, n_train_points):  
    batch_sizes = [4, 32, 128]  
    n_filters = [16, 32, 64]  
    n_ConvFilters = [16, 32]  
    kernel_sizes = [3]  
    optimizers = ['adam', 'SGD', 'RMSprop']  
    histories = []  
  
    TrialNumber = 0  
  
    global best_model  
    best_model = [0,0,0,'optimizer']  
    global best_metrics  
    best_metrics = [10**5, 0.0]  
    global best_trial  
    best_trial = 0  
  
    for bs1 in batch_sizes:  
        for nf in n_filters:  
            for ks in kernel_sizes:  
                for os in optimizers:
```

# 2+D Grid search - results

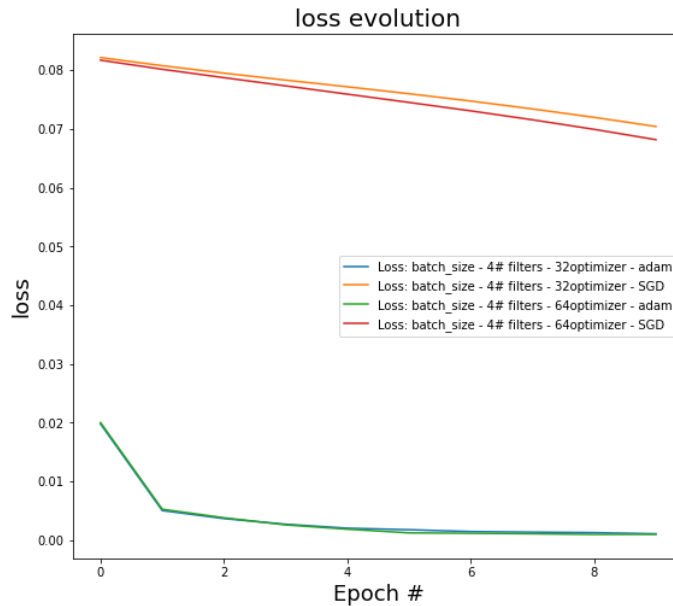
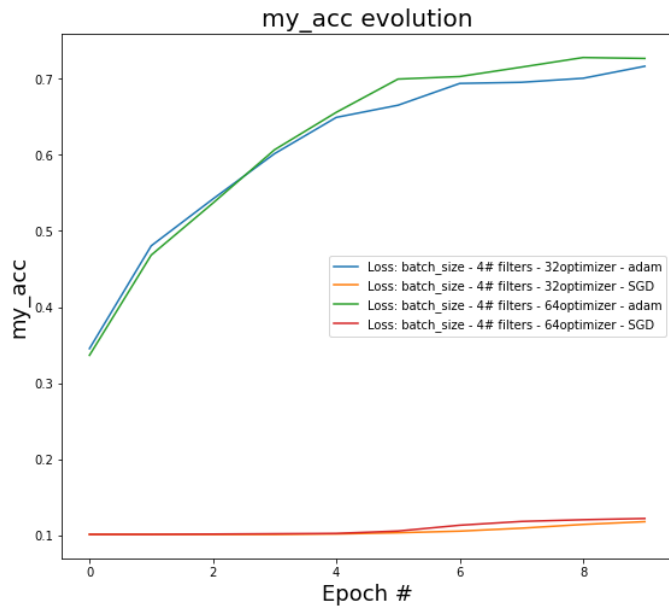
my\_acc evolution: batchsize - 128 # filters -32 optimizer - adam



loss evolution: batchsize - 128 # filters -32 optimizer - adam

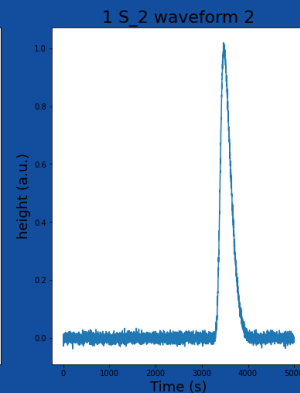
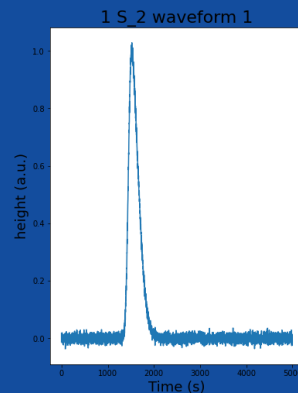
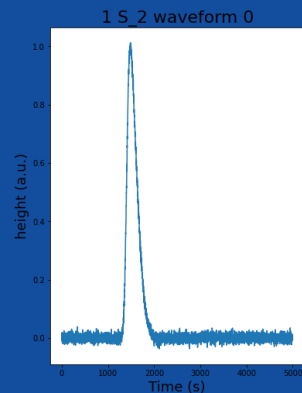


# 2+D Grid search – best model

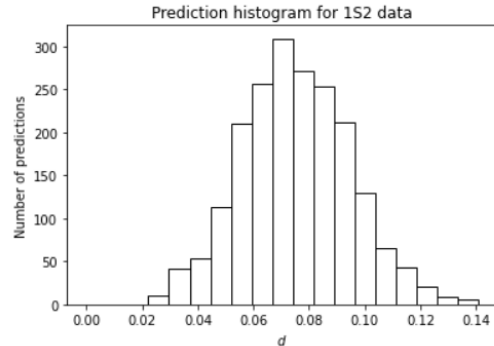
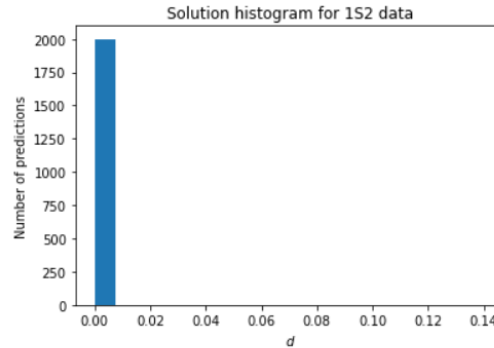


# 5. Testing on 1S2 waveforms

Checked waveforms and normalized them



# Preliminary results – not the optimal parameters



## 6. 1S2 and 2S2 distinction

# Creation of new labels and reformatting

```
#equal number of 2S2 and 1S2 curves with d = 0

#retrieve 2S2 waveforms with d = 0
X2S2_d0 = X_train3[y_train2[:,0]<0.01]
#create labels
N = 2000
y2S2 = np.zeros((N,1))
y2S2[:,0] = 2
y1S2 = np.zeros((N,1))
y1S2[:,0] = 1
X2S2_d0 = X2S2_d0[:N]

max_ = np.shape(X2S2_d0)[0]

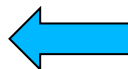
#concatenate
y_final = np.concatenate((y2S2[:max_,:], y1S2[:max_,:]), axis = 0)
X_final = np.concatenate((X2S2_d0[0:max_,:], X_test1S2[0:max_,:]), axis = 0)

#shuffle
y_final_ = y_final.reshape(2*max_, 1, 1)
together = np.concatenate((X_final, y_final_), axis = 1)
np.random.shuffle(together)

#retrieve
X_Final = together[:,5000,:]
y_Final = together[:,5000,:]
print(np.shape(y_Final))
print(np.shape(X_Final))
#print(y_Final)

#split
X_final_train, X_final_test, y_final_train, y_final_test = train_test_split(X_Final, y_Final, test_size=0.2, random_state=0)
```

```
y_FFinal_train = keras.utils.to_categorical(y_final_train.values, 2)
y_FFinal_test = keras.utils.to_categorical(y_final_test.values, 2)
```



Going back to categorical classification



## Again, creating and training the model

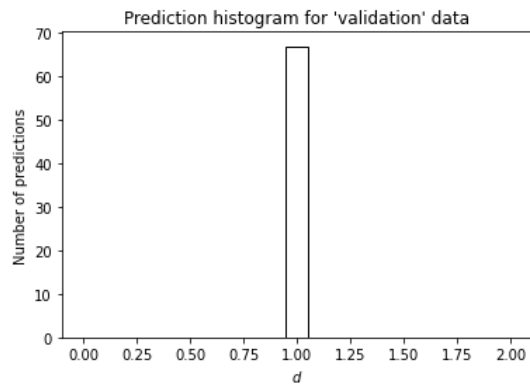
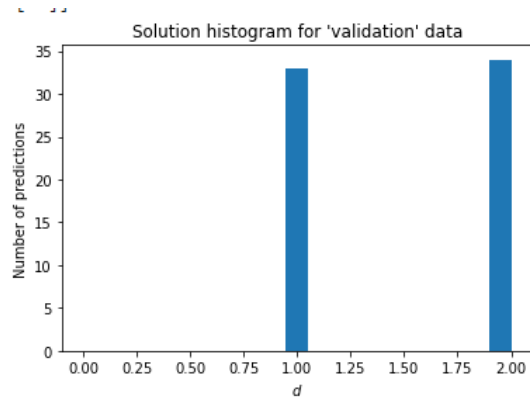
```
early_stopping_monitor = EarlyStopping(monitor='val_loss', min_delta=0.001, patience=5, verbose=1, mode='auto')

optimizer = Adam(learning_rate=0.001)

model.compile(optimizer, loss='mean_squared_error', metrics = 'categorical_accuracy')

# ----- training the model (fitting the data)
history = model.fit(X_final_train, y_FFinal_train,
                    batch_size=4,
                    epochs=10,
                    verbose=1,
                    callbacks=[early_stopping_monitor],
                    validation_data=(X_final_test, y_FFinal_test))
```

# Results...



**Thanks!**